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(71) Applicant (for all designated States except US): **SURGICAL DEVELOPMENT AG [CH/CH]**; Zugerstrasse 74, CH-6341 Baar (CH).

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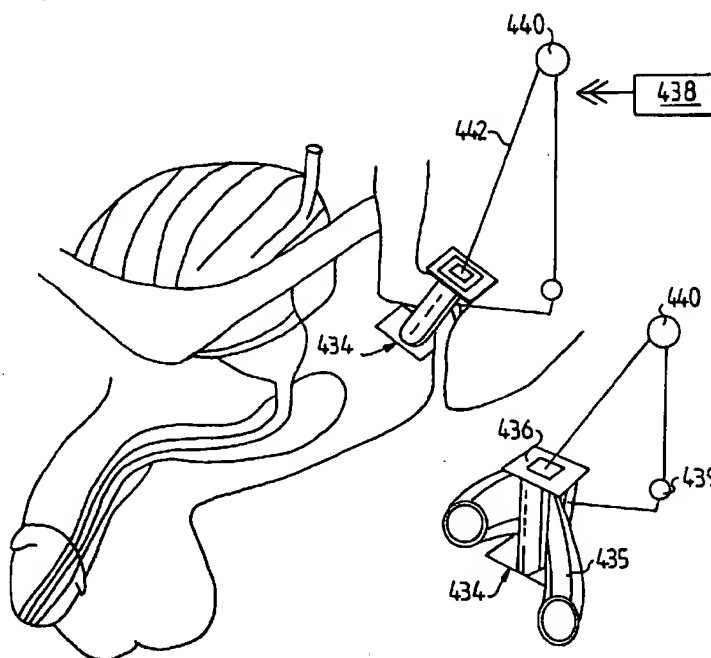
(72) Inventor; and
(75) Inventor/Applicant (for US only): **FORSELL, Peter** [SE/CH]; Kirchgasse 4, CH-6313 Menzingen (CH).
(74) Agents: **HAGSTRÖM, Leif et al.**; Bergenstråhle & Lindvall AB, P.O. Box 17704, S-118 93 Stockholm (SE).

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(54) Title: **ANAL INCONTINENCE TREATMENT APPARATUS**



(57) Abstract: An anal incontinence treatment apparatus comprises an adjustable restriction (434) device implanted in a patient, who suffers from anal incontinence, and engaging a portion of the colon or rectum (435) of the patient to restrict the faecal passageway therein. An adjustment device (436) mechanically adjusts the restriction device to restrict or release the faecal passageway, i.e. to normally close the faecal passageway and open the faecal passageway when the patient wants to relieve himself or herself.

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For two-letter codes and other abbreviations, refer to the "Guidance Notes on Codes and Abbreviations" appearing at the beginning of each regular issue of the PCT Gazette.

ANAL INCONTINENCE TREATMENT APPARATUS

The present invention relates to an anal incontinence
5 treatment apparatus for treatment of a patient, who suffers
from anal incontinence, comprising an adjustable restriction
device implantable in the patient for engaging a portion of
the colon or rectum of the patient to restrict a faecal
passageway therein, and an operable adjustment device
10 implantable in the patient for adjusting the restriction
device to change the restriction of the faecal passageway.

Anal incontinence is a wide-spread disease. Several kinds
of sphincter plastic surgery are used today to remedy anal
incontinence. There is a prior manually operated sphincter
15 system in an initial clinical trial phase where a hydraulic
sphincter system connected to an elastic reservoir (balloon)
placed in the scrotum is developed. A disadvantage of this
system is that thick, hard fibrosis is created around the
reservoir by pump movements making the system useless sooner
20 or later. Another disadvantage is that the use of hydraulic
fluid always entails a risk of fluid leaking from the
implanted hydraulic system.

A prime object of the present invention is to provide an
25 anal incontinence treatment apparatus in which the risk of
liquid leaking from hydraulic components of the apparatus
implanted in the patient's body is substantially reduced or
completely eliminated.

A further object of the invention is to provide an anal
30 incontinence treatment apparatus, which does not require a
manual manipulation of a combined reservoir and pump mechanism
implanted in the scrotum or labia majora region of the

patient.

These objects are obtained by an apparatus of the kind stated initially characterised in that the adjustment device is adapted to mechanically adjust the restriction device.

5 The adjustment device may be non-manually operated, i.e. the adjustment device may be operated by any powered operation device, not manipulated by touching the skin of the patient. Preferably, the adjustment device is adapted to adjust the restriction device in a non-invasive manner.

10 The adjustment device may adjust the restriction device in a non-thermal manner or in a non-magnetic manner, i.e. magnetic forces may not be involved when adjusting the restriction device.

15 The restriction device preferably is adapted to control, suitably steplessly, the cross-sectional area of the faecal passageway, i.e. to open and close the faecal passageway.

20 In the various embodiments hereinafter described the restriction device generally forms an at least substantially closed loop. However, the restriction device may take a variety of different shapes, such as the shape of a square, rectangle or ellipse. The substantially closed loop could for example be totally flat, i.e. thin as seen in the radial direction. The shape of restriction device may also be changed during use, by rotation or movements of the restriction device
25 in any direction.

30 A physical lumen, like the colon or rectum, is often easier to restrict by contracting at least two opposite or different side walls of the lumen against each other. The expression "colon or rectum" should be understood to mean the rectum extended all the way out to the anal sphincter and following the passage of the large intestine in the other direction.

The restriction device may comprise an adjustable cuff, a clamp or a roller for bending the colon or rectum to restrict the faecal passageway therein. Such a cuff, clamp or roller may also be utilized for squeezing the colon or rectum against human material inside the body of the patient for an example the sacral bone of the patient.

Preferably, the restriction device comprises an elongated restriction member and forming means for forming the restriction member into at least a substantially closed loop around the portion of the colon or rectum, wherein the loop defines a restriction opening, whereby the adjustment device adjusts the restriction member in the loop to change the size of the restriction opening.

The restriction device may be designed for implantation in the abdomen or retroperitoneum of the patient and preferably may engage the colon or rectum.

The adjustment device may be incorporated in the restriction device as well as controlled by hydraulic means.

In accordance with a preferred first adjustment principle, the adjustment device mechanically adjusts the longitudinal extension of the elongated restriction member in a loop form.

In a preferred embodiment of the invention utilizing the first adjustment principle, the restriction member comprises a main portion and two elongated end portions, and the adjustment device establishes longitudinal relative displacement between the end portions of the restriction member, so that the size of the restriction opening is adjusted. The forming means may comprise any suitable known or conventional device capable of practising the desired function, such as a spring material forming the elongated restriction member into the loop, so that the restriction

opening has a predetermined size, and the adjustment device may adjust the restriction member against the spring action of the spring material. In other words, the restriction member may comprise a spring clip. The spring material may be
5 integrated in the restriction member.

Preferably, the adjustment device comprises a movement transferring member, suitably a drive wheel, in engagement with at least one of the end portions of the restriction member and operable to displace the one end portion relative
10 to the other end portion of the restriction member. The drive wheel may advantageously be in engagement with both of the end portions of the restriction member and be operable to displace said end portions relative to each other. An elongated flexible drive shaft may be operatively connected to the drive
15 wheel, for transferring manual or motor generated power from a location remote from the restriction member. In its simplest embodiment, the drive wheel may comprise a pulley in frictional engagement with the restriction member. As an alternative, a gear rack may be formed on at least one of the
20 end portions of the restriction member and the drive wheel may comprise a gear wheel in mesh with the gear rack. Other suitable known or conventional mechanisms may also or alternatively be used as the adjustment device.

The movement transferring member may alternatively
25 comprise at least one cylinder and a piston, which is movable therein and is connected to one of the end portions of the restriction member, the piston being operable to longitudinally displace the one end portion of the restriction member relative to the other end portion of the restriction
30 member. Alternatively, the movement transferring means may comprise two interconnected cylinders and two pistons in the respective cylinders connected to said end portions,

respectively, of the restriction member, the pistons being operable to longitudinally displace the end portions of the restriction member relative to each other. Other known or conventional devices also or alternatively can be used as the movement transferring member.

A motor, which is fixed relative to the main portion of the restriction member and has a rotating drive shaft operatively connected to the movement transferring member, may be positioned relative to the elongated restriction member such that the drive shaft extends transverse thereto. Alternatively, the motor may be positioned relative to the elongated restriction member such that the drive shaft extends substantially tangentially to the loop of the restriction member.

In another embodiment of the invention utilizing the first adjustment principle, the elongated restriction member is longitudinally resilient and the adjustment device comprises a contraction device for longitudinally contracting the resilient restriction member. Preferably, the elongated restriction member comprises a substantially nonresilient main portion and an end portion forming an elongated helical spring, which is contractible by the contraction device. The contraction device may suitably comprise an elongated flexible pulling member connected to the main portion of the restriction member and extending through the helical spring to contract the helical spring against an arresting member, which is fixed relative to the main portion of the restriction member. The pulling member may extend in an elongated tube joined at one end thereof to the arresting member, so that a motor remote from the restriction member may be attached to the other end of the elongated tube and pulls the pulling member through the tube to contract the helical spring.

In yet another embodiment of the invention utilizing the first adjustment principle, the elongated restriction member comprises an elongated helical spring having a free end, and a body to which the spring is nonrotatably secured at its opposite end. The adjustment device rotates the helical spring in one direction to enlarge the coils of the helical spring to longitudinally contract the spring and to rotate the spring in the opposite direction to reduce the size of the coils of the spring to longitudinally extend the spring. As a preferred alternative, the restriction member comprises a further elongated helical spring having a free end and nonrotatably secured to the body at its opposite end, and the adjustment device comprises a drive shaft having two opposite end portions connected to the springs, respectively, at their free ends, the helical coils forming left and right hand helices, respectively. The adjustment device may alternatively comprise a gearing having an input shaft and two opposite aligned output shafts connected to the helical springs, respectively, at their free ends, the input shaft being connected to said output shafts so that the output shafts rotate in the opposite directions upon rotation of the input shaft, the helical coils forming the same helices.

In accordance with a second adjustment principle, the adjustment device mechanically adjusts the restriction member so that at least a portion of a radially innermost circumferential confinement surface formed by the restriction member is substantially radially displaced.

In one embodiment of the invention utilizing the second adjustment principle, the restriction member comprises an elongated voltage responsive element forming part of the confinement surface and capable of bending into a bow in response to a voltage applied across the element, the radius

of curvature of the bow being adjustable by changing the level of the voltage.

In another embodiment of the invention utilizing the second adjustment principle, the adjustment device changes the diameter of an elastic annular element of the restriction member, which forms the confinement surface. Preferably, the forming means comprises a substantially rigid outer annular element coaxially surrounding the elastic annular element, and the adjustment device comprises means for pulling the elastic annular element radially outwardly towards the outer annular element to expand the elastic annular element. For example, the pulling means may comprise a plurality of threads secured to the elastic annular element along the circumference thereof and running from the elastic annular element via guide members attached to the outer annular element.

In yet another embodiment of the invention utilizing the second adjustment principle, the forming means comprises a substantially rigid outer annular element, and the restriction member comprises an elongated helical spring extending internally along the outer annular element and contacting the latter. The helical spring forms part of the circumferential confinement surface and has a free end. The restriction member further comprises a body to which the spring is nonrotatably secured at its opposite end. The adjustment device rotates the helical spring in one direction to enlarge the coils of the spring to contract the circumferential confinement surface and rotates the spring in the opposite direction to reduce the size of the coils of the spring to expand the circumferential confinement surface. As an alternative, which is preferred, the restriction member comprises two elongated helical springs forming part of the circumferential confinement surface and connected to the body of the restriction member. The

adjustment device rotates each spring in one direction to enlarge the coils of the spring to contract the circumferential confinement surface and rotates the spring in the opposite direction to reduce the size of the coils of the spring to expand the circumferential confinement surface.

In accordance with a third adjustment principle, the restriction member comprises at least two separate elements, at least one of which is pivoted so that it may turn in a plane in which the the restriction member extends, and the adjustment device turns the pivoted element to change the size of the restriction opening. Preferably, the restriction member comprises a plurality of separate pivoted elements disposed in series, each pivoted element being pivoted in the plane, and the adjustment device turns all of the pivoted elements to change the size of the restriction opening. For example, the pivoted elements may comprise lamellae arranged like the conventional adjustable aperture mechanism of a camera.

In accordance with a fourth adjustment principle, the adjustment device folds at least two foldable frame elements of the restriction member towards each other. Preferably, the foldable frame elements comprise two substantially or partly semi-circular frame elements which are hinged together so that the semi-circular elements are swingable relative to each other from a fully open state in which they form part of a circle to a fully folded state in which they form part of a semi-circle. The same principal may be used with the swingable parts mounted together in one end and not in the other end. Alternatively, the restriction device may comprises two preferable rigid articulated clamping elements positioned on opposite or different sides of the colon or rectum, and the adjustment device turns the clamping elements toward each other to clamp the colon or rectum between the clamping

elements, thereby restricting the faecal passageway in the colon or rectum.

In accordance with a fifth adjustment principle, the adjustment device turns the restriction member around a longitudinal extension thereof, the elongated restriction member being elastic and varying in thickness as seen in a cross-section therethrough. Suitably, the elongated restriction member comprises an elastic belt.

In accordance with a sixth adjustment principle, the adjustment device changes the size of the restriction opening such that the outer circumferential confinement surface of the restriction member is changed.

In accordance with a seventh adjustment principle, the adjustment device changes the size of the restriction opening such that the outer circumferential confinement surface of the restriction member is unchanged.

In accordance with an eighth adjustment principle, the elongated restriction member may be flexible, and the adjustment device pulls a first portion of the flexible restriction member from a second portion of the flexible restriction member opposite the first portion in the loop to squeeze the colon or rectum between the opposite lengths of the elongated flexible restriction member to restrict the faecal passageway in the colon or rectum.

In accordance with a ninth adjustment principle, the restriction device comprises at least two elements on opposite or different sides of the colon or rectum, and the adjustment device decreases the distance between the elements to squeeze the colon or rectum between the elements, thereby restricting the faecal passageway in the colon or rectum. It is also possible to use only one element and squeeze the colon or rectum against human bone or tissue. The elements above may as

well as all the restriction members mentioned in this application be everything from rigid to soft.

In accordance with a tenth adjustment principle, the restriction device bends or rotates a portion of colon or rectum to restrict the faecal passageway in the same. For example, the restriction device may comprise at least two bending members, such as cylindrical or hour-glass shaped rollers, positioned on opposite or different sides of the colon or rectum and displaced relative to each other along the colon or rectum, and the adjustment device may move the bending members against the colon or rectum to bend it to restrict the faecal passageway in the colon or rectum. Suitably, the displacement members may comprise rollers. The restriction device may also rotate a portion of the colon or rectum. The bending or rotating members may have any shape or form and be either hydraulic or non-inflatable.

Alternatively, the two bending members one placed more distal than the other may be rotated in opposite direction relative to each other. With interconnecting material for example flexible bands between the holding members a restriction will occur between the bending members when they are rotated.

The restriction device may in all applicable embodiments take any shape and be either hydraulic or non-inflatable.

In all of the above-described embodiments of the invention the adjustment device is conveniently operated by an operation device, which may comprise a servo means and/or a motor, preferably a reversible electric motor. The motor may be fixed directly to or be placed in association with the restriction device, or alternatively be located remote from the restriction device, advantageously in the abdomen or pelvic region or subcutaneously or in the retroperitoneum of

the patient. In the latter alternative the motor is advantageously connected to the adjustment device by a flexible power transmission conduit to permit a suitable positioning of the motor in the abdomen of the patient. The
5 motor may be manually activatable, for example by an implanted switch.

In some of the above described embodiments of the invention, however, the adjustment device may conveniently be operable by a hydraulic operation device, which preferably is
10 manually activatable. The hydraulic operation device may advantageously include a hydraulic servo to facilitate manual activation. As an alternative, the hydraulic operation device may be powered by an electric motor, which may be manually activatable or controlled by remote control means. The
15 components of such a hydraulic operation device may be placed in association with the restriction device and/or be located at a suitable place in the abdomen or be implanted subcutaneously.

More specifically, a reservoir may be provided containing
20 a predetermined amount of fluid for supplying the hydraulic operation device with fluid. The reservoir defines a chamber for the predetermined amount of fluid and the hydraulic operation device changes the volume of the chamber. The hydraulic operation device may comprise first and second wall
25 portions of the reservoir, which are displaceable relative to each other to change the volume of the chamber of the reservoir. The first and second wall portions of the reservoir may be designed to be displaceable relative to each other by manual manipulation thereof, preferably to permit manual
30 pushing, pulling or rotation of any of the wall portions in one direction. Alternatively, the wall portions may be displaceable relative to each other by magnetic means (such as

a permanent magnet and magnetic material reed switch, or other known or conventional magnetic devices), hydraulic means or electrical control means such as an electric motor. The magnetic means, hydraulic means, or electrical control means
5 may all be activated by manual manipulation, preferably using a subcutaneously located manually manipulatable means. This control may be indirect, for example via a switch.

The hydraulic operation device may operate the adjustment device with fluid from the reservoir in response to a
10 predetermined first displacement of the first wall portion of the reservoir relative to the second wall portion of the reservoir, to adjust the restriction device to open the faecal passageway, and to operate the adjustment device with fluid from the reservoir in response to a predetermined second
15 displacement of the first wall portion of the reservoir relative to the second wall portion of the reservoir, to adjust the restriction device to close the faecal passageway. In this embodiment, no pump is used, only the volume of the reservoir is varied. This is of great advantage compared to
20 the solution described below when a pump is used to pump fluid between the reservoir and the adjustment device because there is no need for a non-return valve and it is still possible to have fluid going both to and from the reservoir.

As an alternative, the hydraulic operation means may
25 comprise a pump for pumping fluid between the reservoir and the adjustment device. The pump may pump fluid both to and away from the adjustment device. A mechanical manual solution is proposed in which it is possible to pump in both directions just by pushing an activating member in one direction. Another
30 alternative is a pump pumping in only one direction and an adjustable valve to change the direction of fluid to either increase or decrease the amount of fluid in the reservoir.

This valve may be manipulated manually, mechanically, electrically, magnetically, or hydraulically. Any kind of motor could of course be used for all the different operations as well as wireless remote solutions. The pump may comprise a
5 first activation member for activating the pump to pump fluid from the reservoir to the adjustment device and a second activation member for activating the pump to pump fluid from the adjustment device to the reservoir. The activation members may be operable by manual manipulation, preferably to permit
10 manual pushing, pulling or rotating thereof in one direction. Suitably, at least one of the activation members is adapted to operate when subjected to an external pressure exceeding a predetermined magnitude.

Alternatively, at least one of the first and second
15 activating members may be operable by magnetic means, hydraulic means or electrical control means such as an electric motor. The magnetic means, hydraulic means, or electrical control means may all be activated by manual manipulating means preferably located subcutaneously. This
20 activation may be indirect, for example via a switch.

Advantageously, especially when manual manipulation means are used, a servo means could be used. With servo means less force is needed for operating the adjustment device. The term "servo means" encompasses the normal definition of a servo
25 mechanism, i.e. an automatic device that controls large amounts of power by means of very small amounts of power, but may alternatively or additionally encompass the definition of a mechanism that transfers a weak force acting on a moving element having a long stroke into a strong force acting on
30 another moving element having a short stroke. The servo means may comprise a motor, preferably an electric motor, which may be reversible.

Alternatively, a reverse servo may be employed. The term "reverse servo" is to be understood as a mechanism that transfers a strong force acting on a moving element having a short stroke into a weak force acting on another moving element having a long stroke; i.e. the opposite function of the above-defined alternative mechanism of a normal servo mechanism. A first closed hydraulic system that controls another closed hydraulic system in which hydraulic means of the adjustment device is incorporated may be used. Minor changes in the amount of fluid in a smaller reservoir of the first system could then be transferred by the reverse servo into major changes in the amount of fluid in a larger reservoir in the second system. In consequence, the change of volume in the larger reservoir of the second system affects the hydraulic means of the adjustment device. For example, a short stroke that decreases the volume of the smaller reservoir will cause the larger reservoir to supply the adjustment device with a large amount of hydraulic fluid, which in turn results in a long mechanical adjustment stroke on the restriction device. The great advantage of using such a reverse servo is that the larger volume system could be placed inside the abdomen or retroperitoneum where there is more space and still it would be possible to use manual manipulation means of the smaller system subcutaneously. The smaller reservoir could be controlled directly or indirectly by a fluid supply means. The fluid supply means may include another small reservoir, which may be placed subcutaneously and may be activated by manual manipulation means. Both the servo and reverse servo may be used in connection with all of the various components and solutions described in the present specification.

Preferably, the reverse servo comprises hydraulic means

and a main fluid supply reservoir and eventually an additional fluid supply reservoir. Both reservoirs define a chamber containing hydraulic fluid, and the hydraulic means comprises first and second wall portions of the main fluid supply reservoir, which are displaceable relative to each other to change the volume of the chamber of the main fluid supply reservoir. The hydraulic means may control the adjustment device indirectly, e.g. via an increased amount of fluid in the main fluid supply reservoir, in response to a predetermined first displacement of the first wall portion of any of the reservoirs relative to the second wall portion of the reservoir to close the faecal passageway, and to control the adjustment device in response to a second displacement of the first wall portion of any reservoir relative to the second wall portion, to indirectly adjust the restriction device to open the faecal passageway. The wall portions of the reservoirs may be designed to be displaceable relative to each other by manual manipulation thereof or be displaceable relative to each other by manually pushing, pulling or rotating any of the wall portions of the reservoir in one direction. Alternatively, the wall portions of the main fluid supply reservoir may be displaceable relative to each other by magnetic means, hydraulic means or electric control means including an electric motor.

The magnetic means, hydraulic means, or electrical control means may all be activated by manually manipulated means preferably located subcutaneously. This control may be indirect for example via a switch.

Even in the broadest embodiment of the invention the adjustment device may comprise a servo means. The servo means may comprise a hydraulic operation means, an electrical control means, a magnetic means, mechanical means or a manual

manipulation means. The hydraulic operation means, electrical control means, mechanical means or magnetic means may be activated by manual manipulating means. Using a servo system will save the use of force when adjusting the adjustment
5 device, which may be of importance in many applications, for example when a battery cannot put out enough current although the total energy in the battery is more than enough to power the system.

In accordance with a preferred embodiment of the
10 invention, the apparatus comprises implantable electrical components including at least one, or only one single voltage level guard and a capacitor or accumulator, wherein the charge and discharge of the capacitor or accumulator is controlled by use of the voltage level guard. As a result, there is no need
15 for any implanted current detector and/or charge level detector for the control of the capacitor, which makes the apparatus simple and reliable.

All solutions may be controlled by a wireless remote control for controlling the adjustment device. The remote
20 control may advantageously be capable of obtaining information related to the faecal passageway or the pressure against the restriction device or colon or rectum or other important physical parameters and of commanding the adjustment device to adjust the restriction device in response to obtained
25 information. With the wireless remote control the apparatus of the invention is conveniently controlled by the patient when he so desires, which is of great advantage compared to the prior art procedures. With the remote control the apparatus of the invention is conveniently controlled to adjust the
30 implanted restriction device to release the faecal passageway when the patient wants to relieve himself or herself.

The apparatus may further comprise a pressure sensor for

directly or indirectly sensing the pressure against the restriction device and the restriction device may control the blood flow in response to signals from the pressure sensor. The pressure sensor may be any suitable known or conventional
5 pressure sensor such as shown in U.S. patents 5540731, 4846181, 4738267, 4571749, 4407296 or 3939823; or an NPC-102 Medical Angioplasty Sensor. The adjustment device preferably non-invasively adjusts the restriction device to change the size of the cross-sectional area.

10 The adjustment device and/or other energy consuming components of the apparatus may be energised with wirelessly transmitted energy from outside the patient's body or be powered by an implanted battery or accumulator.

The apparatus may further comprise an implanted energy
15 transforming device for transferring wireless energy directly or indirectly into kinetic energy for operation of the restriction device. The energy transforming device may, preferably directly, transform the wireless energy in the form of sound waves into electric energy for operation of the
20 restriction device. Suitably the energy transforming device comprises a capacitor adapted to produce electric pulses from the transformed electric energy.

The apparatus of the invention may further comprise an energy transfer means for wireless transfer of energy from
25 outside the patient's body to the adjustment device and/or other energy consuming implantable components of the apparatus. The energy transfer means may be adapted to intermittently transfer the energy, preferably electric energy, in the form of a train of energy pulses for direct use
30 in connection with the energising of the energy consuming components of the apparatus. An implanted capacitor having a capacity less than 0,1 μF may be used for producing the train

of energy pulses.

A motor may be implanted for operating the adjustment device, wherein the energy transfer means is adapted to directly power the motor with transferred energy.

5 Alternatively, or in combination with the motor, a pump may be implanted for operating the adjustment device, wherein the energy transfer means is adapted to transfer wireless energy in the form of electromagnetic waves for direct power of the pump. Preferably, the pump is not a plunger type of pump, but
10 may comprise a peristaltic or membrane pump.

The energy transfer means preferably transfers wireless energy in the form of electromagnetic waves. However, for safety radio waves may be excluded.

Alternatively, the energy transferred by the energy
15 transfer means may comprise an electric field or a magnetic field.

Most preferred, the energy transferred by the energy transfer means comprises a signal.

Preferably, the wireless remote control comprises a
20 separate signal transmitter or receiver and a signal receiver or transmitter implanted in the patient. For example, the signal transmitter and signal receiver may transmit and receive a signal in the form of digital pulses, which may comprise a magnetic or electric field. Alternatively, which is
25 preferred, the signal transmitter and signal receiver may transmit and receive an electromagnetic wave signal, a sound wave signal or a carrier wave signal for a remote control signal. The receiver may comprise an implanted control unit for controlling the adjustment device in response to a control
30 signal from the signal transmitter.

The apparatus of the invention may further comprise an implanted energiser unit for providing energy to energy

consuming implanted components of the apparatus, such as electronic circuits and/or a motor for operating the adjustment device. The apparatus may comprise an external energy transmitter for transmitting wireless energy, wherein
5 the energiser unit is adapted to transform the wireless energy into electric energy. An implanted electric motor may operate the adjustment device and the energiser unit may be adapted to power the electric motor with the electric energy transformed from the wireless energy.

10 The energiser unit may comprise a battery and a switch operable by the wireless energy transmitted by the external transmitter, for connecting the battery to the implanted energy consuming components of the apparatus in an "on" mode when the switch is powered by the wireless energy and to keep
15 the battery disconnected from the energy consuming components in a "standby" mode when the switch is not powered.

The control unit may power such an implanted motor with energy provided by the energiser unit in response to a control signal received from the signal transmitter. Any known or
20 conventional signal transmitter or signal receiver that is suitable for use with a human or mammal patient may be provided as the signal transmitter or signal receiver of the invention.

Generally, all of the above signals may comprise
25 electromagnetic waves, such as infrared light, visible light, laser light, micro waves, or sound waves, such as ultrasonic waves or infrasonic waves, or any other type of wave signals. The signals may also comprise electric or magnetic fields, or pulses. All of the above-mentioned signals may comprise
30 digital signals. The signals may be carried by a carrier wave signal, which in an alternative embodiment may be the same signal as the wireless energy signal. Preferably a digital

control signal may be carried by an electromagnetic wave signal. The carrier wave or control signal may be amplitude or frequency modulated.

The motor may be any type of motor, such as a pneumatic, 5 hydraulic or electric motor and the energiser unit may power the motor with pressurized gas or liquid, or electric energy, depending on the type of motor. Where the motor is an electric motor, it may power pneumatic or hydraulic equipment.

The energiser unit may comprise a power supply and the 10 control unit may power the motor with energy from the power supply. Preferably, the power supply is an electric power supply, such as a battery, and the motor is an electric motor. In this case, the battery also continuously powers at least part of the circuitry of the signal receiver in a standby mode 15 between the adjustments, in order to keep the signal receiver prepared for receiving signals transmitted from the signal transmitter.

The energiser unit may transform energy from the control signal, as the control signal is transmitted to the signal 20 receiver, into electric energy for powering the implanted electronic components. For example, the energiser unit may transform the energy from the control signal into a direct or alternating current.

In case there is an implanted electric motor for 25 operating the adjustment device the energiser unit may also power the motor with the transformed energy. Advantageously, the control unit directly powers the electric motor with electric energy, as the energiser unit transforms the signal energy into the electric energy. This embodiment is 30 particularly simple and does not require any recurrent invasive measures for exchanging empty power supplies, such as batteries, that is required in the first embodiment described

above. The motor may also be directly powered with wirelessly transmitted electromagnetic or magnetic energy in the form of signals, as the energy is transmitted. All the various functions of the motor and associated components described in the present specification may be used where applicable.

For adjustment devices of the type that requires more, but still relatively low, power for its operation, the energiser unit may comprise a rechargeable electric power supply for storing the electric energy obtained and the control unit may power the electric motor with energy from the rechargeable electric power supply in response to a control signal received from the signal transmitter. In this case, the rechargeable power supply can be charged over a relatively long time (e.g. a few seconds up to a half hour) without powering the electric motor.

The electric power supply suitably comprises an inexpensive simple capacitor. In this case, the electric motor may be a stepping motor. In all embodiments the motor may preferably be able to perform a reversing function.

The signal transmitter may transmit an electromagnetic signal and the energiser unit may draw radiant energy from the electromagnetic wave signal, as the latter is transmitted to the signal receiver, and transform the radiant energy into electric energy.

Alternatively, the energiser unit may comprise a battery or an accumulator, an electrically operable switch adapted to connect the battery to the signal receiver in an on mode when the switch is powered and to keep the battery disconnected from the signal receiver in a standby mode when the switch is unpowered, and a rechargeable electric power supply for powering the switch. The control unit may power the electric motor with energy from the battery in response to a control

signal received from the signal transmitter, when the switch is in its on mode. Advantageously, the energiser unit may transform wave energy from the control signal, as the latter is transmitted to the signal receiver, into a current for
5 charging the rechargeable electric power supply, which suitably is a capacitor. Energy from the power supply is then used to change the switch from off (standby mode) to on. This embodiment is suited for adjustment devices of the type that require relatively high power for their operation and has the
10 advantage that the electronic circuitry of the signal receiver does not have to be powered by the battery between adjustments. As a result, the life-time of the battery can be significantly prolonged. The switch may be switched with magnetic, manual or electric energy.

15 As an example, the signal transmitter may transmit an electromagnetic wave signal and the energiser unit may draw radiant energy from the electromagnetic wave signal, as this is transmitted to the signal receiver, and may transform the radiant energy into said current. The energiser unit suitably
20 comprises a coil of the signal receiver for inducing an alternating current as the electromagnetic wave signal is transmitted through the coil and a rectifier for rectifying the alternating current. The rectified current is used for charging the rechargeable power source.

25 Alternatively, the signal transmitter and receiver may solely be used for a control signal and a further pair of signal transmitter and receiver may be provided for transferring signal energy to implanted components. By such a double system of signal transmitters and receivers the
30 advantage is obtained that the two systems can be designed optimally for their respective purposes, namely to transmit a control signal and to transfer energy from an energy signal.

Accordingly, the apparatus may further comprise an external energy transmitter for transmitting wireless energy, wherein the energiser unit comprises a battery and an operable switch for connecting the battery to the signal receiver in an on mode when the switch is powered and for keeping the battery disconnected from the signal receiver in a standby mode when the switch is unpowered, and the external energy transmitter powers the switch. Suitably, the energy transmitter may directly power the switch with the wireless energy to switch into the on mode. As should be realized by a skilled person, in many of the above-described embodiments of the invention the adjustment device may be operated by control means or manual manipulation means implanted under the skin of the patient, such as a pump, an electrical switch or a mechanical movement transferring means. In the manual embodiment it is not necessary to use a motor for operating the adjustment device.

In embodiments including hydraulic transmission means, an injection port connected to the hydraulic means may be provided for enabling, normally single, once-and-for-all, calibration of the amount of fluid in the hydraulic system.

In all embodiments a motor may be operatively connected to the adjustment device. A reversing device may be implanted in the patient for reversing the motor.

The adjustment device may be adapted to hydraulically adjust the restriction device by using hydraulic means which is devoid of hydraulic fluid of the kind having a viscosity that substantially increases when exposed to heat or a magnetic field, i.e. the hydraulic fluid would not become more viscous when exposed to heat or influenced by magnetic forces.

A pressure sensor may be used to directly or indirectly sense the pressure against the restriction device or the colon

or rectum to avoid occurrence of necrosis of the human tissue. The restriction device may be controlled in response to signals from the pressure sensor. The motor which preferably is used to adjust the restriction device must then be capable of performing a reversible function, that is to say, be
5 of performing a reversible function, that is to say, be capable of reversing the driving direction of the motor.

Preferably the adjustment device is directly energised with wirelessly transmitted energy from outside the patient's body. The implanted energy transforming device transforms
10 wireless energy directly or indirectly into kinetic energy for operation of the restriction device. In accordance with another embodiment it would also be possible to use an implanted accumulator or battery and control this implanted energy source from outside the patient's body to supply energy
15 to the adjustment device or other energy consuming parts of the implanted apparatus.

All the above-described various components, such as the motor, pump and capacitor, may be combined in the different embodiments where applicable. Also the various functions
20 described in connection with the above embodiments of the invention may be used in different applications, where applicable.

The invention also provides a method for treating a
25 patient suffering from anal incontinence comprising surgically implanting in the body of the patient an adjustable restriction device which directly engages the colon or rectum of the patient like an artificial sphincter around the faecal passageway therein, normally closed, and when desired,
30 mechanically adjusting the restriction device to temporarily open the faecal passageway.

The adjustable restriction device preferably is implanted

in the base or prolongation of the patient's rectum. It would also be possible to use two or more restricting devices engaging the colon or rectum.

The invention further provides a method for treating anal
5 incontinence, comprising the steps of placing at least two
laparascopical trocars in the body of a patient suffering from
anal incontinence, inserting a dissecting tool through the
trocars and dissecting an area of the colon or rectum in the
abdominal or pelvic or retroperitoneal surroundings, placing
10 at least one adjustable restriction device in the dissected
area engaging the rectum or colon, adjusting the restriction
device to normally restrict the faecal passageway in the
rectum or colon, and adjusting the restriction device to open
the faecal passageway when the patient wants to relieve
15 himself or herself. A mechanically adjustable restriction
device may be used when practising this method, preferably in
a non-manual manner, i.e. without touching subcutaneously
implanted components of the apparatus.

The method may further comprise implanting a source
20 of energy in the patient and providing a control device for
controlling the source of energy from outside the patient's
body to supply energy to the restriction device.

The invention is described in more detail in the
25 following with reference to the accompanying drawings, in
which

FIGURE 1 is a schematic sectional view of a preferred
first embodiment of the anal incontinence treatment apparatus
in accordance with the invention;

30 FIGURES 2 and 3 are cross-sectional views taken along the
lines II-II and III-III, respectively, of FIGURE 1;

FIGURES 4 and 5 schematically show two alternative

designs of the embodiment of FIGURE 1;

FIGURE 6 schematically illustrates a motor arrangement for the design according to FIGURE 5;

FIGURE 7 is a schematic sectional view of a second
5 embodiment of the apparatus in accordance with the invention;

FIGURE 8 schematically illustrates a hydraulic transmission conduit for the embodiment of FIGURE 7;

FIGURE 9 is a schematic sectional view of a third embodiment of the apparatus in accordance with the invention;

10 FIGURE 10 is a modification of the embodiment of FIGURE 9;

FIGURE 11 is a schematic view of a fourth embodiment of the apparatus in accordance with the invention;

FIGURES 12 and 13 are enlarged details of the embodiment
15 of FIGURE 11;

FIGURE 14 is a cross-section along the line XIV-XIV of FIGURE 11;

FIGURE 15 is a schematic view of a fifth embodiment of the apparatus in accordance with the invention;

20 FIGURE 16 is an enlarged detail of FIGURE 15;

FIGURE 17 is a cross-section along the line XVII-XVII of FIGURE 15;

FIGURES 18 to 21 are schematic sectional views of a sixth, seventh, eighth and ninth embodiments, respectively, of
25 the apparatus in accordance with the invention;

FIGURES 22 and 23 illustrate a fully open and a reduced restriction opening, respectively, of the embodiment of FIGURE 21;

FIGURE 24 is a schematic view of a tenth embodiment of
30 the apparatus in accordance with the invention;

FIGURE 25 is an enlarged detail of the embodiment of FIGURE 24;

FIGURES 26 and 27 illustrate a fully open and a reduced restriction opening, respectively, of the embodiment of FIGURE 24;

FIGURE 28 schematically illustrates a cushion arrangement
5 for protecting the tissue of the patient;

FIGURE 29A-D is a block diagram of four different principal embodiments of the invention;

FIGURE 30A-D are cross-sectional views of a pump mechanism according to FIGURE 29C, which pumps fluid in
10 opposite directions by mechanically pushing a wall portion in only one direction;

FIGURE 31 is a cross-sectional view of a reservoir having a variable volume controlled by a remote control motor, in accordance with a particular embodiment of the principal
15 embodiment shown in FIGURE 29B or 30B;

FIGURE 32 is a cross-sectional view of a reservoir having a variable volume adjustable by manual manipulation, in accordance with a particular embodiment of the principal embodiment shown in FIGURE 29B or 29D;

FIGURE 33A is a front view of a hydraulic, pneumatic or
20 mechanical reverse servo system in accordance with a particular embodiment of the principal embodiment shown in FIGURE 29D;

FIGURE 33B is a cross-sectional view taken along line VB-
25 VB of FIGURE 33A;

FIGURE 34 is a block diagram illustrating remote control components of the apparatus of the invention;

FIGURE 35 is a schematic view of a circuitry used for the system of the block diagram of FIGURE 34;

FIGURES 36A and 36B are schematic views of an eleventh
30 embodiment of the apparatus in accordance with the invention;

FIGURES 37A and 37B are schematic views of a twelfth

embodiment of the apparatus in accordance with the invention;

FIGURE 38 is a schematic view of a thirteenth embodiment of the apparatus in accordance with the invention;

FIGURES 39A, 39B and 39C are a schematic front view and
5 schematic sectional views, respectively, of a fourteenth embodiment of the apparatus in accordance with the invention;

FIGURES 40A through 44B are five modifications of the embodiment of FIGURES 39A-39C;

FIGURE 45 illustrates the apparatus of the invention with
10 a restriction device implanted around the colon.

Referring to the drawing figures, like reference numerals designate identical or corresponding elements throughout the several figures.

15 FIGURES 1-3 show a preferred embodiment of the anal incontinence treatment apparatus of the invention comprising a restriction device having an elongated restriction member in the form of a circular resilient core 2 with two overlapping end portions 4,6. The core 2 defines a substantially circular
20 restriction opening and is enclosed in an elastic soft hose 8 except at a releasable and lockable joint 10 of the core 2, which when released enables application of the core 2 with its hose 8 around a tissue of a patient, such as the colon or rectum or anus. The materials of all of these elements are
25 bio-compatible so that the patient's body will not reject them. A mechanical adjustment device 12 for mechanically adjusting the longitudinal extension of the core 2 to change the size of the restriction opening comprises a drive wheel 14 in frictional engagement with the overlapping end portions 4,6 of
30 the core 2. The drive wheel 14 is journalled on a holder 16 placed in the hose 8 and provided with two counter pressure rollers 18,20 pressing the respective end portions 4, 6 of the

core 2 against the drive wheel 14 to increase the frictional engagement there between. An electric motor 22 is connected to the drive wheel 14 via a long flexible drive shaft 24 and is moulded together with a remote controlled power supply unit 26
5 in a body 28 of silicone rubber. The length of the flexible drive shaft 34 is selected so that the body 28 can be placed in a desired position in the patient's body, suitably in the abdomen.

When the patient doesn't want to relieve himself
10 (defaecation), he controls the power supply unit 26 to power the electric motor 22 to turn the drive wheel 14 in one direction to reduce the diameter of the core 2, so that the colon or rectum is squeezed and the faecal passageway is restricted. When the patient wishes to relieve himself he
15 controls the power supply unit 26 to power the electric motor 22 to turn the drive wheel 14 in the opposite direction to increase the diameter of the core 2, so that the faecal passageway is open.

Alternatively, a rack gear may be formed on one of the
20 end portions 4,6 of the core 2 and the drive wheel 14 may be replaced by a drive gear wheel connected to the other end portion of the core 2 and in mesh with the rack gear.

FIGURE4 shows an embodiment of the invention which is identical to the embodiment of FIGURES 1-3, except that the
25 motor 22 is encapsulated in a lateral protrusion 30 of the hose 8 so that it is fixed to the core 2 and has a short drive shaft 32 onto which the drive wheel 14 is mounted, and that the motor 22 is positioned relative to the circular core 2 such that the drive shaft 32 extends radially thereto.

30 FIGURE 5 shows an embodiment of the invention which likewise is identical to the embodiment of FIGURES 1-3, except that the motor 22 is encapsulated in the hose 8 so that it is

fixed to the core 2 and has a short drive shaft 32, and that the motor 22 is positioned relative to the core 2 such that the drive shaft 32 extends substantially tangentially to the circular core 2. There is an angular gearing 34 connecting the drive shaft 32 to the drive wheel 14.

FIGURE 6 shows a suitable arrangement for the motor 22 in the embodiment of FIGURE 5, comprising a first clamping member 36 secured to one end portion of the core 2 and a second clamping member 38 secured to the other end portion 6 of the core 2. The motor 22 is secured to the first clamping member 36 and is operatively connected to a worm 40 via a gear transmission 42. The worm 40 is journaled at its opposite ends on holders 44 and 46, which are rigidly secured to the clamping member 36 and the motor 22, respectively. The second clamping member 38 has a pinion in mesh with the worm 40. When the motor 22 is powered the worm 40 rotates and will thereby pull the end portion 6 of the core 2 in one or the opposite longitudinal direction, so that the diameter of the substantially circular core 2 is either increased or decreased.

FIGURE 7 shows an embodiment of the invention in which the elongated restriction member comprises a core 48 and a helical spring 50. A spring contracting means in the form of a flexible pulling member 52, i.e. a string, wire or cable, is connected to the core 48 at one end thereof and extends through the helical spring 50. A hydraulic motor in the form of a cylinder/piston unit 54 is adapted to pull the flexible pulling member 52 to contract the helical spring 50 against an arresting member 56, which is fixed relative to the core 48. A tube 58 hinged to the arresting member 56 extends between the cylinder/piston unit 54 and the arresting member 56, the flexible pulling member 52 running through the tube 58 and

being connected to the piston of the cylinder/piston unit 54.

FIGURE 8 shows a similar embodiment in which a hydraulic transmission conduit 59 is provided between two piston-cylinder assemblies 54, for use as the hydraulic motor/device
5 in FIGURE 7.

FIGURE 9 shows an embodiment of the invention in which the restriction member comprises two elongated helical springs 60 and 62 having free ends, and a body 64 to which the springs 60,62 are nonrotatably secured at their opposite ends.
10 The body 64 comprises two separate parts secured to opposite end portions of the enclosing elastic hose 8 and is designed with a releasable and lockable joint between the separate parts. An adjustment device in the form of a drive shaft 66 has two opposite end portions connected to the helical springs
15 60,62, respectively, at their free ends. The coils of the springs 60,62 form left and right hand helices, respectively.

A motor 68 is adapted to rotate the drive shaft 66 in one direction to enlarge the coils of the helical springs 60,62 to longitudinally contract the springs 60,62 and to rotate the
20 drive shaft 66 in the opposite direction to reduce the size of the coils of the springs 60,62 to longitudinally extend the springs 60,62. Thus, the elongated helical springs 60,62 defines a restriction opening, the size of which is increased when the springs 60,62 are extended and decreased when the
25 springs 60,62 are contracted.

FIGURE 10 shows an embodiment according to the invention which is identical to the embodiment of FIGURE 9, except that the adjustment device comprises a gearing having an input shaft 72 and two opposite aligned output shafts 74 and 76
30 connected to the helical springs 60 and 62, respectively, at their free ends. The input shaft 72 is connected to the output shafts 74,76 such that they rotate at opposite directions upon

rotation of the input shaft 72. The coils of the springs 60, 62 form the same helices.

FIGURES 11-14 show an embodiment of the device of the invention in which a hydraulic motor comprises two interconnected cylinders 78 and 80 and two pistons 82 and 84 in the respective cylinders 78,80. The cylinders 78,80 have a common fluid supply inlet member 86, which together with the cylinders 78,80 takes the shape of a Y-pipe. The restriction member comprises an elongated resilient arcuate core 88. The adjustment device comprises two bars 90 and 92 secured to opposite ends of the core 88 and connected to the pistons 82 and 84, respectively. The core 88 defines a restriction opening and is provided with a releasable and lockable joint 94 (FIGURE 13) to permit application of the core 88 around the tissue. The core 88 and the cylinders 90,92 are enclosed by a soft elastic hose 96 except at the joint 94 and the inlet member 86. The hose 96 has an outer tubular wall 98 and a central coaxial inner tubular wall 100, which is fixed to the outer wall 98 by spoke members 102 (FIGURE 14). The core 88 is loosely fit in the inner tubular wall 100. By supplying fluid to or withdrawing fluid from the inlet 86 the pistons 82 and 84 will move towards or from each other, so that the restriction opening defined by the core 88 is changed by the longitudinal displacement of the bars 90,92.

FIGURES 15-17 show an embodiment of the invention which is identical to the embodiment of FIGURES 11-14, except that the adjustment device comprises an elongated voltage responsive element 104 secured to the opposite ends of the core 88, so that the core 88 and the element 104 form the restriction member. The element 104 is capable of bending inwardly into a bow in response to a voltage applied across the element 104. The radius of curvature of the bow is

adjustable by changing the level of the voltage applied to element 104.

FIGURE 18 shows an embodiment of the invention comprising a loop forming means in the form of a substantially rigid
5 outer circular element 106 with a releasable and lockable joint 108. In this embodiment the restriction member comprises an elastic inner circular element 110 formed by the innermost wall portion of an elastic hose 112 extending along the outer element 106. The inner circular element 110 is disposed
10 concentrically within the outer circular element 106. The adjustment device comprises a plurality of threads 114 secured to the elastic inner element 110 along the circumference thereof and running from the inner element 110 via guide members 116 attached to the outer element 106. By pulling all
15 the threads 114 the inner elastic element 110 is pulled under expansion radially outwardly towards the outer element 106.

FIGURE 19 shows an embodiment which is identical to the embodiment of FIGURE, 9, except that it comprises a loop forming means in the form of a substantially rigid outer
20 circular element 118 supporting the helical springs 60,62, and a soft elastic inner wall 120 extending along the springs 60,62. When the motor 68 rotates the helical springs 60, 62 in a direction that enlarges the coils of the springs 60,62, the coils are forced by the rigid outer element 118 to expand
25 radially inwardly thereby reducing the size of the restriction opening formed by the circumferential confinement surface of the restriction member (springs 60,62 and body 64).

FIGURE 20 shows an embodiment of the invention in which a restriction member comprises a plurality of arcuate lamellae
30 122 arranged like the conventional adjustable aperture mechanism of a camera. The adjustment device, not shown, is conventional and is operated by a motor 124 to adjust the

lamellae 122 to change the size of an restriction opening defined by the lamellae 122.

FIGURES 21-23 show an embodiment of the invention in which a restriction member comprises two semi-circular elements 126 and 128 which are hinged together such that the
5 semi-circular elements 126,128 are swingable relative to each other between a fully open state in which they substantially form a circle, illustrated in FIGURE, 22 and an angular state, in which the size of the restriction opening defined by the
10 semi-circular elements 126,128 is reduced, illustrated in FIGURE, 23. The adjustment device, not shown, is conventional and is operated by a motor 130 to swing the semi-circular elements 126,128 relative to each other.

FIGURES 24-27 show an embodiment of the invention in which a restriction member comprises an elastic belt 130
15 forming a circle and having a substantially oval cross-section. The restriction member 130 is provided with a releasable and lockable joint 132. An elastic double walled hose 134 encloses the belt 130 except at the joint 132. The
20 adjustment device, not shown, is conventional and is operated by a motor 136 to turn the belt 130 around the longitudinal extension thereof between a fully open state, in which the inner broader side of the belt 130 forms a substantially cylindrical surface, illustrated in FIGURE 26, and a reduced
25 open state, in which the inner broader side of the belt 130 forms a substantially conical surface, illustrated in FIGURE 27.

FIGURE 28 schematically illustrates a cushion arrangement for protecting the human tissue, comprising a plurality of
30 cushions 138 disposed in series along a substantially circular holding member 140. This cushion arrangement may be utilized in any of the above described embodiments of the invention.

FIGURES 29A-D provide a block diagram of four different hydraulic transmission configurations. FIGURE 29A shows an adjustment device 202, a separate reservoir 204, a one way pump 206 and an alternate valve 208. FIGURE 29B shows the
5 adjustment device 202 and an adjustable reservoir 210. FIGURE 29C shows the adjustment device 202, a two-way pump 212 and the reservoir 204. FIGURE 29D shows a reverse servo system with a first closed system controlling a second system. The servo system comprises an adjustable servo reservoir 210 and a
10 passive adjustable fluid supply reservoir 214. Any of the reservoirs can be the active reservoir, either the servo reservoir 210 or the fluid supply reservoir 214. The reservoir 214 controls a larger adjustable reservoir 216, which is used for the operation of the adjustment device 202 for changing
15 the restriction opening of the restriction member.

FIGURES 30A-D are cross-sectional views of a pump mechanism adapted to pump fluid in both directions only by mechanically pushing a separate sealing wall portion 218 in one direction. FIGURE 30A shows a piston 220 pushed forwards
20 against a spring 222 towards the wall portion 218 and located in a pump housing 224 conducting fluid from a right upper fluid passage 226 of the housing 224 to a left fluid passage 228 of the housing 224. A main valve 230 is open and a nonreturn valve 232 is closed. FIGURE 30B illustrates the
25 first pump movement in which the piston 220 has moved forwards and reaches the wall portion 218. FIGURE 30C illustrates how the piston 220 moves backwards by the action of the spring 222. The main valve 230 is now closed and the nonreturn valve 232 is open for fluid from the right upper passage 226. FIGURE
30 30D illustrates how the piston 220 is moved further downwards from its position according to FIGURE 30B while pushing the wall portion 218 downwards against a second spring 234 that

is stronger than spring 222, so that fluid escapes from a right lower fluid passage 236. When moving the piston 220 backwards from the position of FIGURE 30D, fluid enters the left fluid passage 228 and a valve 238 in the lower right fluid passage 236 closes.

FIGURE 31 is a cross-sectional view of a reservoir 240 defining a chamber 242, the volume of which is variable and is controlled by a remote controlled motor 244, in accordance with FIGURE 29B or 29D. The reservoir 240 and the motor 244 are placed in a housing 246. The chamber 242 is varied by moving a large wall 248. The wall 248 is secured to a nut 250, which is threaded on a rotatable spindle 252. The spindle 252 is rotated by the motor 244 via an angular gearing, which comprises two conical gear wheels 254 and 256 in mesh with each other. The motor 244 is powered by a battery 258 placed in the housing 246. A signal receiver 260 for controlling the motor 244 is also placed in the housing 246. Alternatively, the battery 258 and the signal receiver 260 may be mounted in a separate place. The signal receiver may comprise any known or conventional device which is capable of receiving a control signal and then operating the motor 244.

FIGURE 32 is a cross-sectional view of a reservoir 262 defining a chamber 264, the volume of which is variable and is controlled by manual manipulation. A gable wall portion 266 of an open ended inner cylindrical housing 68 is adapted to be pushed downwards to fit in a desired locking groove 270 of a plurality of locking grooves 270 on the mantle wall of the cylindrical housing 268, to reduce the volume of the chamber 64. The inner cylindrical housing 268 is suspended by springs 272 and is telescopically applied on an outer cylindrical housing 274. When pushing the inner cylindrical housing 268 it moves downwards relative to the outer cylindrical housing 274

causing the gable wall portion 266 to release from the locking groove 270 and move upwards relative to the inner cylindrical housing 268. When the inner housing 268 is moved upwardly by the action of the springs 272 the volume of the chamber 264 is increased.

FIGURE 33A and 33B show a reverse servo comprising a main ring-shaped fluid reservoir 276 defining a chamber 278, the volume of which is variable. Centrally positioned in the main ring-shaped reservoir 276 there is a servo fluid reservoir 280 defining a chamber 282, the volume of which is variable. The chamber 282 of the servo reservoir 280 is significantly smaller than the chamber 278 of the main reservoir 276. The two reservoirs 276 and 280 are situated between two opposite separate walls 284 and 286, and are secured thereto. When changing the amount of fluid in the servo reservoir 280, the two opposite walls 284, 286 are moved towards or away from each other, whereby the volume of the chamber 278 of the main reservoir 276 is changed.

FIGURE 34 shows the basic parts of a remote control system of the apparatus of the invention including a motor, for instance the electric motor 22. In this case, the remote control system is based on the transmission of an electromagnetic wave signal, often of a high frequency in the order of 100 kHz - 1 GHz, through the skin 330 of the patient. In FIGURE 34, all parts placed to the left of the skin 330 are located outside the patient's body and all parts placed to the right of the skin 330 are implanted in the patient's body.

An external signal transmitting antenna 332 is to be positioned close to a signal receiving antenna 334 implanted in the patient's body close to the skin 330. As an alternative, the receiving antenna 334 may be placed for example inside the abdomen of the patient. The receiving

antenna 334 comprises a coil, approximately 1-100 mm, preferably 25 mm in diameter, wound with a very thin wire and tuned with a capacitor to a specific high frequency. A small coil is chosen if it is to be implanted under the skin of the patient and a large coil is chosen if it is to be implanted in the abdomen of the patient. The transmitting antenna 332 comprises a coil having about the same size as the coil of the receiving antenna 334 but wound with a thick wire that can handle the larger currents that is necessary. The coil of the transmitting antenna 332 is tuned to the same specific high frequency as the coil of the receiving antenna 334.

An external control unit 336 comprises a microprocessor, a high frequency electromagnetic signal generator and a power amplifier. The microprocessor of the control unit 336 is adapted to switch on/off the generator and to modulate signals generated by the generator to send digital information via the power amplifier and the antennas 332,334 to an implanted control unit 338. To avoid that accidental random high frequency fields trigger control commands, digital signal codes are used. A keypad placed on the external control unit 336 is connected to the microprocessor thereof. The keypad is used to order the microprocessor to send a digital signal to either increase or decrease the size of the restriction opening defined by the loop of the restriction member (e.g. as described above). The microprocessor starts a command by applying a high frequency signal on the antenna 332. After a short time, when the signal has energized the implanted parts of the control system, commands are sent to increase or decrease the size of the restriction opening of the restriction member in predefined steps. The commands are sent as digital packets in the form illustrated below.

Start pattern, 8 bits	Command, 8 bits	Count, 8 bits	Checksum, 8 bits
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The commands are sent continuously during a rather long time period (e.g. 30 seconds or more). When a new increase or decrease step is desired the Count byte is increased by one to allow the implanted control unit 338 to decode and understand that another step is demanded by the external control unit 336. If any part of the digital packet is erroneous, its content is simply ignored.

10 Through a line 340, an implanted energiser unit 326 draws energy from the high frequency electromagnetic wave signal received by the receiving antenna 334. The energiser unit 326 stores the energy in a power supply, such as a large capacitor, powers the control unit 338 and powers the electric
15 motor 22 via a line 342.

The control unit 338 comprises a demodulator and a microprocessor. The demodulator demodulates digital signals sent from the external control unit 336. The microprocessor of the control unit 338 receives the digital packet, decodes it
20 and, provided that the power supply of the energiser unit 326 has sufficient energy stored, sends a signal via a signal line 344 to the motor 22 to either increase or decrease the size of the restriction opening of the restriction member depending on the received command code.

25 Alternatively, the energy stored in the power supply of the energiser unit may only be used for powering a switch, and the energy for powering the motor 22 may be obtained from another implanted power source of relatively high capacity, for example a battery. In this case the switch is adapted to

connect the battery to the control unit 338 in an "on" mode when the switch is powered by the power supply and to keep the battery disconnected from the control unit in a "standby" mode when the switch is unpowered.

5 With reference to FIGURE 35, the remote control system schematically described above will now be described in accordance with a more detailed embodiment. The external control unit 336 comprises a microprocessor 346, a signal generator 348 and a power amplifier 350 connected thereto. The
10 microprocessor 346 is adapted to switch the signal generator 348 on/off and to modulate signals generated by the signal generator 348 with digital commands that are sent to implanted components of the device of the invention. The power amplifier 350 amplifies the signals and sends them to the external
15 signal transmitting antenna 332. The antenna 332 is connected in parallel with a capacitor 352 to form a resonant circuit tuned to the frequency generated by the signal generator 348.

The implanted signal receiving antenna coil 334 forms together with a capacitor 354 a resonant circuit that is tuned
20 to the same frequency as the transmitting antenna 332. The signal receiving antenna coil 334 induces a current from the received high frequency electromagnetic waves and a rectifying diode 360 rectifies the induced current, which charges a storage capacitor 358. A coil 356 connected between
25 the antenna coil 334 and the diode 360 prevents the capacitor 358 and the diode 360 from loading the circuit of the signal receiving antenna 334 at higher frequencies. Thus, the coil 356 makes it possible to charge the capacitor 358 and to transmit digital information using amplitude modulation.

30 A capacitor 362 and a resistor 364 connected in parallel and a diode 366 forms a detector used to detect amplitude modulated digital information. A filter circuit is formed by a

resistor 368 connected in series with a resistor 370 connected in series with a capacitor 372 connected in series with the resistor 368 via ground, and a capacitor 374, one terminal of which is connected between the resistors 368,370 and the other
5 terminal of which is connected between the diode 366 and the circuit formed by the capacitor 362 and resistor 364. The filter circuit is used to filter out undesired low and high frequencies. The detected and filtered signals are fed to an implanted microprocessor 376 that decodes the digital
10 information and controls the motor 22 via an H-bridge 378 comprising transistors 380,382,384 and 386. The motor 22 can be driven in two opposite directions by the H-bridge 378.

The microprocessor 376 also monitors the amount of stored energy in the storage capacitor 358. Before sending signals to
15 activate the motor 22, the microprocessor 376 checks whether the energy stored in the storage capacitor 358 is enough. If the stored energy is not enough to perform the requested operation, the microprocessor 376 waits for the received signals to charge the storage capacitor 358 before activating
20 the motor 22.

FIGURES 36A and 36B show an embodiment of the apparatus of the invention comprising a restriction device 402 having an elongated flexible restriction member 404, such as a belt, a cord or the like. The flexible member 404 extends in a loop
25 around the tissue, suitably the rectum or colon or its prolongation. (Alternatively, the flexible member 404 may comprise two separate parts on opposite sides of the colon or rectum or the prolongation thereof). One portion 404A of member 404 is attached to a frame 408 and another portion 404B
30 of member 404 opposite portion 404A in the loop of the flexible member 404 is connected to an adjustment device 410, which is fixed to the frame 408. The adjustment device 410

pulls the flexible member 404 in the direction from portion 404A to squeeze the colon or rectum or the prolongation thereof between two opposite lengths of the flexible member 404 to thereby restrict the faecal passageway in the colon or rectum 406 or the prolongation thereof, see FIGURE 36A, and releases the colon or rectum or the prolongation thereof from the flexible member 404 to thereby increase the faecal passageway to allow defaecation, see FIGURE 36B.

FIGURES 37A and 37B show an embodiment of the apparatus of the invention comprising a restriction device 412 having two plate or bar elements 414 on opposite sides of the rectum 406. An adjustment device 416 moves the elements 412 in parallel towards each other to squeeze the rectum 406 between the elements 412 to thereby restrict the blood flow in the rectum 406, see FIGURE 37A, and moves the elements 412 away from each other to release the rectum 406, see FIGURE 37B.

FIGURE 38 shows an embodiment of the apparatus of the invention comprising a restriction device 418 having two rigid articulated clamping elements 420 positioned on opposite sides of the rectum 406. An adjustment device 422 turns the clamping elements 420 toward each other to clamp the rectum 406 between the clamping elements 420 to thereby restrict the faecal passageway in the rectum 406, and turns the clamping elements 420 away from each other to release the rectum 406 from the clamping elements 420 to thereby increase the restriction of the faecal passageway to allow defaecation.

FIGURES 39A, 39B and 39C show an embodiment of the apparatus of the invention comprising a restriction device 424 having three bending members in the form of cylindrical rollers 426, 428 and 430 displaced relative one another in a row along the rectum 406 and positioned alternately on opposite sides of the rectum 406. (Alternatively, each roller

426, 428 and 430 may take the shape of an hour-glass.) An adjustment device 432 moves the two outer rollers 426,430 laterally against the rectum 406 in one direction and the intermediate roller 428 against the rectum 406 in the opposite
5 direction to bend the rectum to thereby restrict the faecal passageway in the rectum 406, see FIGURE 39B. To increase the faecal passageway to allow defaecation, the adjustment device 432 moves the rollers 426-430 away from the rectum 406 to release the latter from the rollers 426-430, see FIGURE 39C.

10 FIGURES 40A through 44B schematically illustrates modifications of the above embodiment according to FIGURES 39A-39C. Thus, FIGURES 40A and 40B show an embodiment similar to that of FIGURES 39A-39C except that the bending members are oval and not rotatable. FIGURES 41A and 41B show an embodiment
15 similar to that of FIGURES 40A and 40B except that the oval bending members are rotatable to release the rectum, see FIGURE 41A, and squeeze the rectum, see FIGURE 41B. FIGURES 42A and 42B show an embodiment similar to that of FIGURES 39A-39C except that the intermediate roller has a changeable
20 diameter to release the rectum, see FIGURE 42A, and squeeze the rectum, see FIGURE 42B. FIGURES 43A and 43B show an embodiment similar to that of FIGURES 37A-37C except that the rigid elements are replaced by two cylindrical rollers positioned on opposite sides of the rectum. Finally, FIGURES
25 44A and 44B show an embodiment substantially similar to that of FIGURES 43A and 43B except that the restriction device is curved to form an S-shaped curvature of the rectum.

FIGURE 45 schematically illustrates how any of the above-described embodiments of the anal incontinence treatment
30 apparatus of the invention may be implanted in a patient. Thus, the apparatus comprises an adjustable restriction device 434 extending around the the rectum 435 of the patient and a

motor operated adjustment device 436 for mechanically adjusting the restriction device 434 to squeeze the rectum to thereby restrict the faecal passageway in the rectum. The motor, not shown, is integrated in the adjustment device 436 and is reversible to operate the adjustment device 436 to release the rectum from the restriction device 434 to allow defaecation. A wireless remote control of the apparatus comprises an external signal transmitter 438 incorporated in a portable remote-control unit and an implanted signal receiver 440, which comprises a control unit for controlling the adjustment device 436 in response to a control signal, for example an electromagnetic wave signal, from the transmitter 438. The signal receiver 440 further comprises an energiser unit which transfers energy from the control signal transmitted by the transmitter 438 into electric energy for energy consuming implanted components of the apparatus, such as the motor for operating the adjustment device 436. The electric energy is conducted via an implanted conductor 442 from the signal receiver 440 to the motor. When the patient needs to relieve himself (defaecation), he readily uses the portable remote control unit to activate the implanted adjustment device 436 to temporarily adjust the implanted restriction device 434 to start release the faecal passageway to allow defaecation.

25 A pressure sensor 439 is implanted for sensing the pressure on the restriction device 434. The control unit of the signal receiver 449 controls the adjustment device 436 to release the restriction device 434 in response to the pressure sensor 439 sensing an abnormal high pressure.

30 There are a number of other conceivable alternative embodiments of the invention that give the same result as the above-described embodiments. For example, the microprocessor

of the external and implanted, respectively, control unit may be replaced by discrete components. The power amplifier of the external control unit may be omitted if the signals generated by the signal generator are strong enough. Therefore the
5 invention is to be accorded the broadest interpretation of the appended claims to encompass all equivalent structures and assemblies.

CLAIMS

1. An anal incontinence treatment apparatus for treatment
5 of a patient, who suffers from anal incontinence, comprising
an adjustable restriction device
(2;48;60,62;88;110;122;126,128;130;434) implantable in the
patient for engaging a portion of the colon or rectum of the
patient to restrict a faecal passageway therein, and an
10 operable adjustment device (12;52;66;90,92;104;110;436)
implantable in the patient for adjusting the restriction
device to change the restriction of the faecal passageway,
characterised in that the adjustment device is adapted to
mechanically adjust the restriction device.

15

2. An apparatus according to claim 1, wherein the
adjustment device (12;52;66;90,92;104;110) is adapted to
adjust the restriction device in a non-magnetic or non-thermal
manner.

20

3. An apparatus according to claim claim 1 or 2, wherein
the adjustment device is powered.

4. An apparatus according to any one of claims 1-3,
25 wherein the restriction device is non-inflatable.

30

5. An apparatus according to any of claims 1-4, wherein
the restriction device is adapted to control the cross-
sectional area of the faecal passageway.

6. An apparatus according to claim 5, wherein the
restriction device is operable to open and close the faecal

passageway.

7. An apparatus according to claim 6, wherein the restriction device is adapted to steplessly control the cross-sectional area of the faecal passageway.

8. An apparatus according to any one of claims 1-7, further comprising a powered operation device for operating the adjustment device.

9. An apparatus according to any one of claims 1-8, wherein the restriction device comprises an element to be placed on one side of said portion of the colon or rectum, and the adjustment device is adapted to squeeze said portion of the colon or rectum between the element and the human bone or tissue to restrict the faecal passageway.

10. An apparatus according to any one of claims 1-8, wherein the restriction device comprises at least one elongated restriction member (2;48;60,62;88) and forming means (10;94;106;108;118;132) for forming the restriction member into at least a substantially closed loop around said portion of the colon or rectum, the loop defining a restriction opening, whereby the adjustment device is adapted to adjust the restriction member in the loop to change the size of the restriction opening.

11. An apparatus according to claim 10, wherein the restriction device comprises several elongated restriction members (2;48;60,62;88) to be formed into at least substantially closed loops around the colon or rectum.

12. An apparatus according to claim 10 or 11, wherein, the adjustment device (12;52;66;90,92) is adapted to adjust the longitudinal extension of the elongated restriction member in said loop to change the size of the restriction opening.

5

13. An apparatus according to claim 12, wherein the restriction member (2;48) comprises a main portion and two elongated end portions (4,6), and the adjustment device (12;52;66;90,92) is adapted to establish longitudinal relative displacement between the end portions of the restriction member, such that the size of the restriction opening (3) is adjusted.

14. An apparatus according to claim 7, wherein the adjustment device (12;52;66;90,92) comprises a movement transferring member (14;40;78,90;80,92) in engagement with at least one of the end portions (4,6) of the restriction member and operable to displace said one end portion relative to the other end portion of the restriction member.

20

15. An apparatus according to claim 14, further comprising a motor (22), which is fixed relative to the main portion of the restriction member (2) and has a rotating drive shaft (32) operatively connected to the movement transferring member (14).

25

16. An apparatus according to claim 15, wherein the motor is positioned relative to the elongated restriction member such that the drive shaft extends in parallel with a chord in said loop of the restriction member.

30

17. An apparatus according to claim 12, wherein the

elongated restriction member (48,50) is longitudinally resilient and the adjustment device comprises a contraction means (52) adapted to longitudinally contract the resilient restriction member.

5

18. An apparatus according to claim 17, wherein the elongated restriction member comprises a substantially nonresilient main portion (48) and an end portion forming an elongated helical spring (50), which is contractible by the
10 contraction means (52).

19. An apparatus according to claim 18, wherein the contraction means comprises an elongated flexible pulling member (52) connected to the main portion (48) of the
15 restriction member and extending through the helical spring (50) to contract the helical spring against an arresting member (56), which is fixed relative to the main portion of the restriction member.

20. An apparatus according to claim 10, wherein the restriction member comprises an elongated helical spring (60) having a free end, and a body (64) to which said spring is nonrotatably secured at its opposite end, the adjustment device (66) being adapted to rotate the helical spring in one
25 direction to enlarge the coils of the helical spring to longitudinally contract the elongated helical spring and to rotate the helical spring in the opposite direction to reduce the size of the coils of the helical spring to longitudinally extend the helical spring.

30

21. An apparatus according to claim 20, wherein the restriction member comprises a further elongated helical

spring (62) having a free end and nonrotatably secured to the body (64) at its opposite end, and the adjustment device comprises a drive shaft (66) having two opposite end portions connected to the helical springs, respectively, at their free
5 ends, the helical coils forming left and right hand helices, respectively.

22. An apparatus according to claim 21, wherein the restriction member comprises a further elongated helical
10 spring (62) having a free end and nonrotatably secured to the body (64) at its opposite end, and the adjustment device comprises a gearing (70) having an input shaft (78) and two opposite aligned output shafts (74,76) connected to the helical springs (60,62), respectively, at their free ends, the
15 input shaft being connected to the output shafts such that the output shafts rotate in the opposite directions upon rotation of the input shaft, the helical coils forming the same helices.

20 23. An apparatus according to claim 10, wherein the restriction member (88;110;122) forms a radially innermost circumferential confinement surface in said loop of the restriction member, and the adjustment device (104;112) is adapted to mechanically adjust the restriction member such
25 that at least a portion of the confinement surface is substantially radially displaced in said loop.

24. An apparatus according to claim 23, wherein the adjustment device comprises an elongated voltage responsive
30 element (104) forming part of the confinement surface and capable of bending into a bow in response to a voltage applied across the element, the radius of curvature of said bow being

adjustable by changing the level of the voltage.

25. An apparatus according to claim 23, wherein the restriction member comprises an elastic annular element (110) forming the confinement surface, and the adjustment device (112) is adapted to change the diameter of the elastic annular element.

26. An apparatus according to claim 23, wherein the forming means comprises a substantially rigid outer annular element (118), and the restriction member comprises an elongated helical spring (60) extending internally along the outer annular element and contacting the latter, the helical spring forming part of the circumferential confinement surface and having a free end, and a body to which the helical spring is nonrotatably secured at its opposite end, the adjustment device being adapted to rotate the helical spring in one direction to enlarge the coils of the helical spring to contract the circumferential confinement surface and to rotate the helical spring in the opposite direction to reduce the size of the coils of the helical spring to expand the circumferential confinement surface.

27. An apparatus according to claim 23, wherein the forming means comprises a substantially rigid outer annular element (118), and the restriction member comprises a first (60) and a second (62) elongated helical spring extending internally along the outer annular element and contacting the latter, the helical springs forming part of the circumferential confinement surface, the first and the second spring, respectively, having a free end, and a body to which the first and the second spring, respectively, is nonrotatably

secured at its opposite end, the adjustment device being adapted to rotate the first and the second spring, respectively, in one direction to enlarge the coils of the spring to contract the circumferential confinement surface and
5 to rotate the first and the second spring, respectively, in the opposite direction to reduce the size of the coils of the spring to expand the circumferential confinement surface.

28. An apparatus according to claim 10, wherein the
10 restriction member comprises at least two separate elements, at least one of which is pivoted such that it is pivoted in a plane in which said loop of the restriction member extends, and the adjustment device is adapted to turn said pivoted element to change the size of said restriction opening.

15

29. An apparatus according to any one of claims 1-8, wherein the restriction device comprises at least two frame elements (126 and 128), which are foldable towards each other by the adjustment device.

20

30. An apparatus according to claim 29, wherein the foldable frame elements comprise two substantially semi-circular frame elements (126 and 128), which are hinged together such that the semicircular elements are swingable
25 relative to each other from a fully open state in which they substantially form a circle to a fully folded state in which they form a semicircle.

31. An apparatus according to claim 10, wherein the
30 elongated restriction member (130) is elastic and varies in thickness as seen in a cross-section therethrough, and the adjustment device is adapted to turn the restriction member

around the longitudinal extension thereof.

32. An apparatus according to claim 10, wherein the forming means comprises a spring material forming the elongated restriction member into the loop, such that the restriction opening has a predetermined size, and the adjustment device is adapted to adjust the restriction member against the spring action of the spring material.

33. An apparatus according to claim 32, wherein the spring material is integrated in the restriction member.

34. An apparatus according to claim 10, wherein the forming means (10;94;106;108;118;132) is adapted to form the restriction member (2;48;60,62;88;110;122;126,128;130) into a loop having a predetermined size or a size selected from several predetermined sizes.

35. An apparatus according to claim 10, wherein the adjustment device (12;52;66;90;104;110) is adapted to change the size of the restriction opening (3) such that the outer circumferential confinement surface of the restriction member (2;48;60,62;88;110;122;126,128;130) is changed.

36. An apparatus according to claim 10, wherein the adjustment device (12;52;66;90;104;110;434) is adapted to change the size of the restriction opening (3) such that the outer circumferential confinement surface of the restriction member (2;48;60,62;88;110;122;126,128;130;436) is unchanged.

30

37. An apparatus according to claim 10, wherein the elongated restriction member (404) is flexible, and the

adjustment device (410) is adapted to pull a first portion (404A) of the flexible restriction member from a second portion (404B) of the flexible restriction member opposite the first portion in the loop to squeeze said portion of the colon or rectum (406) between two opposite lengths of the elongated flexible restriction member to restrict the faecal passageway in said portion of the colon or rectum (406), and to release said portion of the colon or rectum (406) from the flexible restriction member to enlarge the faecal passageway (Figs. 36A, 36B).

38. An apparatus according to any one of claims 1-8, wherein the restriction device (412) comprises at least two elements (414) to be placed on different sides of said portion of the colon or rectum (406), and the adjustment device is adapted to squeeze said portion of the colon or rectum (406) between the elements to restrict the faecal passageway in said portion of the colon or rectum (406), and to release said portion of the colon or rectum (406) from the elements to enlarge the faecal passageway (Figs. 37A, 37B).

39. An apparatus according to any one of claims 1-8 wherein the restriction device (418) comprises at least two articulated clamping elements (420) to be positioned on opposite or different sides of said portion of the colon or rectum (406), and the adjustment device (422) is adapted to turn the clamping elements toward each other to clamp said portion of the colon or rectum (406) between the clamping elements to restrict the faecal passageway in said portion of the colon or rectum (406), and to turn the clamping elements away from each other to release said portion of the colon or rectum (406) from the clamping elements to enlarge the faecal

passageway (Fig. 38).

40. An apparatus according to any one of claims 1-8,
wherein the restriction device is adapted to bend a portion of
5 said portion of the colon or rectum (406) (Figs. 39A-44B).

41. An apparatus according to claim 40, wherein the
restriction device (424) comprises at least two bending
members (426-430) to be positioned on opposite or different
10 sides of said portion of the colon or rectum (406) and to be
displaced relative to each other along the faecal passageway
in said portion of the colon or rectum (406), and the
adjustment device (432) is adapted to move the bending members
against said portion of the colon or rectum (406) to bend it
15 to restrict the faecal passageway, and to move the bending
members away from said portion of the colon or rectum (406) to
release it from the bending members to enlarge the faecal
passageway (Figs. 39A-39C).

20 42. An apparatus according to claim 41, wherein the
bending members comprise rollers.

43. An apparatus according to any one of claims 1-8,
wherein the restriction device is adapted to rotate a portion
25 of the colon or rectum.

44. An apparatus according to claim 8, wherein the
operation device comprises a motor (22;68;124;130;136)
operatively connected to the adjustment device
30 (12;52;66;90,92;104;110).

45. An apparatus according to claim 44, wherein the

operation device comprises a reverse servo connected between the motor and the adjustment device.

46. An apparatus according to claim 44 or 45, comprising
5 an implantable reversing device for reversing the motor.

47. An apparatus according to any of claims 44-46, wherein the motor (22;68;124;130;136) is fixed to the restriction device.

10

48. An apparatus according to any of claims 44-46, wherein the motor (22) is remote from the restriction member (2) and is connected to the adjustment device (14) by a power transmission conduit (24).

15

49. An apparatus according to claim 8, wherein the operation device comprises a servo means.

50. An apparatus according to claim 49, wherein the servo
20 means comprises a motor, preferably an electric motor.

51. An apparatus according to claim 50, wherein the motor is reversible.

25 52. An apparatus according to claim 8, wherein the operation device comprises hydraulic means (54) for operating the adjustment device (52).

53. An apparatus according to claim 52, further
30 comprising a reservoir (204;210;216) containing a predetermined amount of fluid for supplying the hydraulic means with fluid.

54. An apparatus according to claim 53, wherein the reservoir (210) defines a chamber for the predetermined amount of fluid and the hydraulic means (202) is adapted to change
5 the volume of the chamber.

55. An apparatus according to claim 53 or 54, wherein the hydraulic means comprises a pump (212) adapted to pump fluid between the reservoir (204) and the adjustment device (202).
10

56. An apparatus according to any of claims 52-55, wherein the hydraulic means is devoid of any non-return valve.

57. An apparatus according to any one of claims 53-56,
15 wherein the hydraulic means comprises a reverse servo (210,214;276-286).

58. An apparatus according to claim 57, wherein the reverse servo is manually operated.
20

59. An apparatus according to claim 57, wherein the reverse servo is powered.

60. An apparatus according to any of claims 57-59,
25 wherein the hydraulic means comprises first and second wall portions of the reservoir (204), and the reverse servo is adapted to provide relative displacement between the first and second wall portions of the reservoir.

61. An apparatus according to any one of the preceding claims, further comprising a wireless remote control (22,326,332-344) for non-invasively controlling the adjustment
30

device.

62. An apparatus according to claim 61, wherein the remote control (22,326,332-344) comprises a separate signal transmitter and/or receiver (332,336) and an implantable signal receiver and/or transmitter (334,338), for transmitting and/or receiving a control signal.

63. An apparatus according to claim 62, wherein the signal receiver (334,338) comprises a control unit (338) adapted to control the adjustment device (12;52;66;90,92;104;110) in response to the control signal.

64. An apparatus according to claim 63, further comprising an implantable energiser unit (336) for providing energy to energy consuming components of the apparatus to be implanted in the patient.

65. An apparatus according to any of claims 61-64, further comprising an implantable motor (22) for operating the adjustment device (12;52;66;90,92;104;110).

66. An apparatus according to claims 64 and 65, wherein the control unit (338) is adapted to control the energiser unit (336) to power the motor (22) with energy in response to the control signal.

67. An apparatus according to claim 65 or 66, wherein the motor (22) is an electric motor.

68. An apparatus according to claim 64, wherein the energiser unit (326) is adapted to transform energy from the

control signal, as it is transmitted to the signal receiver (334,338), into electric energy.

69. An apparatus according to claim 64 or 68, wherein the energiser unit (26) is adapted to transform energy from the control signal into a direct or alternating current.

70. An apparatus according to claim 68, further comprising an implantable electric motor (22) for operating the adjustment device (12;52;66;90,92;104;110), wherein the energiser unit (326) comprises a rechargeable electric power supply (58) for storing the electric energy and the control unit (338) is adapted to power the electric motor (22) with energy from the rechargeable electric power supply in response to the control signal.

71. An apparatus according to claim 64, wherein the energiser unit (326) comprises a battery, an electrically operable switch adapted to connect the battery to the signal receiver in (334,338) an "on" mode when the switch is powered and to keep the battery disconnected from the signal receiver in a "standby" mode when the switch is unpowered, and a rechargeable electric power supply for powering the switch.

72. An apparatus according to claim 71, wherein the control unit (338) is adapted to power the electric motor (22) with energy from the battery in response to a control signal received from the signal transmitter (332,336), when the switch is in its "on" mode.

73. An apparatus according to claim 64, further comprising an external energy transmitter for transmitting

wireless energy, wherein the energiser unit comprises a battery and a switch operable by the wireless energy transmitted by the external transmitter, for connecting the battery to the signal receiver in an "on" mode when the switch
5 is powered by the wireless energy and to keep the battery disconnected from the signal receiver in a "standby" mode when the switch is unpowered.

74. An apparatus according to claim 1, further comprising
10 an implantable energiser unit (336) for providing energy to energy consuming components of the apparatus to be implanted in the patient.

75. An apparatus according to claim 74, further
15 comprising an external energy transmitter for transmitting wireless energy, wherein the energiser unit is adapted to transform the wireless energy into electric energy.

76. An apparatus according to claim 75, further
20 comprising an implantable electric motor (22) for operating the adjustment device (12;52;66;90,92;104;110), wherein the energiser unit (326) is adapted to power the electric motor (22) with the electric energy transformed from the wireless energy.

25

77. An apparatus according to claim 74, further
comprising an external energy transmitter for transmitting wireless energy, wherein the energiser unit comprises a battery and a switch operable by the wireless energy
30 transmitted by the external transmitter, for connecting the battery to the implantable energy consuming components of the apparatus in an "on" mode when the switch is powered by the

wireless energy and to keep the battery disconnected from the energy consuming components in a "standby" mode when the switch is unpowered.

5 78. An apparatus according to claim 73 or 76, wherein the external energy transmitter is adapted to directly power the switch with the wireless energy to switch into the "on" mode.

10 79. An apparatus according to claim 61, wherein the remote control (22;326;332-344) is capable of obtaining information from implantable components of the apparatus and of commanding the adjustment device (12;52;66;90;104;110) to adjust the restriction device (2;48;60;62;88;110;122;126;128;130;434) in response to
15 obtained information.

20 80. An apparatus according to claim 1, further comprising implantable electrical components including at least one voltage level guard.

21 81. An apparatus according to claim 1, further comprising implantable electrical components including a single voltage level guard.

25 82. An apparatus according to claim 80 or 81, wherein the electrical components are devoid of any current detector and/or charge level detector.

30 83. An apparatus according to any of claims 80-82, further comprising an implantable capacitor or accumulator, wherein the charge or discharge of the capacitor or accumulator is controlled by use of the voltage level guard.

84. An apparatus according to claim 1, further comprising an energy transfer means (22,326,332-344) for wireless transfer of energy from outside the patient's body to the adjustment device and/or other energy consuming implantable components of the apparatus.

85. An apparatus according to claim 84, wherein the energy transfer means is adapted to intermittently transfer the energy in the form of a train of energy pulses for direct use in connection with the energising of the energy consuming components of the apparatus.

86. An apparatus according to claim 85, wherein the energy transfer means is adapted to transfer electric energy, and further comprising an implantable capacitor for producing the train of energy pulses.

87. An apparatus according to claim 83 or 86, wherein the capacitor has a capacity less than 0,1 μ F.

88. An apparatus according to claim 84, further comprising an implantable motor (22) or pump for operating the adjustment device (12;52;66;90,92;104;110), wherein the energy transfer means is adapted to directly power the motor or pump with transferred energy.

89. An apparatus according to claim 1, further comprising an implantable motor or pump for operating the adjustment device, wherein the energy transmission device is adapted to transmit wireless energy in the form of an magnetic field or electromagnetic waves for direct power of the motor or pump,

as the wireless energy is being transmitted.

90. An apparatus according to claim 89, wherein the pump is not a plunger type of pump.

5

91. An apparatus according to claim 84, wherein the energy transfer means is adapted to transfer wireless energy in the form of electromagnetic waves excluding radio waves.

10

92. An apparatus according to claims 84 or 85, wherein the energy transferred by the energy transfer means comprises an electric field or a magnetic field.

15

93. An apparatus according to claims 84 or 85, wherein the energy transferred by the energy transfer means comprises a signal.

20

94. An apparatus according to claim 62 or 93, wherein the signal comprises digital or analog pulses.

95. An apparatus according to claim 94, wherein the digital or analog pulses comprise a magnetic field or an electric field.

25

96. An apparatus according to claim 62, 92 or 93, wherein the signal comprises a wave signal.

30

97. An apparatus according to claim 96, wherein the wave signal comprises an electromagnetic wave signal, a sound wave signal or a carrier wave signal.

98. An apparatus according to any one of the preceding

claims, further comprising a pressure sensor for directly or indirectly sensing the pressure against the restriction device.

5 99. An apparatus according to claim 98, wherein the restriction device is controlled in response to signals from the pressure sensor.

10 100. An apparatus according to claim 1, further comprising an implantable energy transforming device for transforming wireless energy directly or indirectly into energy different than the wireless energy for operation of the restriction device.

15 101. An apparatus according to claim 100, wherein the energy transforming device transforms the wireless energy into kinetic energy for operation of the restriction device.

20 102. An apparatus according to claim 100, wherein the energy transforming device transforms the wireless energy in the form of sound waves into electric energy for operation of the restriction device.

25 103. An apparatus according to any one of the preceding claims, further comprising an implantable reversing device, wherein the restriction device is capable of performing a reversible function and the reversing device reverses the reversible function.

30 104. An apparatus according to any one of the preceding claims, further comprising an implantable accumulator or battery and means for controlling the accumulator or battery

from outside the patient's body to supply energy to the adjustment device and/or other implantable energy consuming components of the apparatus.

5 105. An apparatus according to claim 1, wherein the adjustment device is adapted to adjust the restriction device in a non-invasive or non-manual manner.

10 106. An apparatus according to claim 1, further comprising an adjustment device for adjusting the restriction device to change the restriction of the faecal passageway, wherein the adjustment device is adapted to mechanically adjust the restriction device, or adapted to hydraulically adjust the restriction device by using hydraulic means which
15 is devoid of hydraulic fluid of the kind having a viscosity that substantially increases when exposed to heat or a magnetic field.

20 107. An apparatus according to claim 102, wherein the energy transforming device transforms the wireless energy in the form of sound waves directly into electric energy.

25 108. An apparatus according to claim 102, 107 or 84, wherein the energy transforming device comprises a capacitor.

 109. An apparatus according to claim 108, wherein the capacitor is adapted to produce electric pulses from the transformed electric energy.

30 110. An apparatus according to claim 59, wherein the reverse servo comprises a motor, preferably an electric motor.

111. An apparatus according to claim 110, wherein the motor is reversible.

112. An apparatus according to claim 97, wherein the carrier signal is frequency, amplitude or frequency and amplitude modulated.

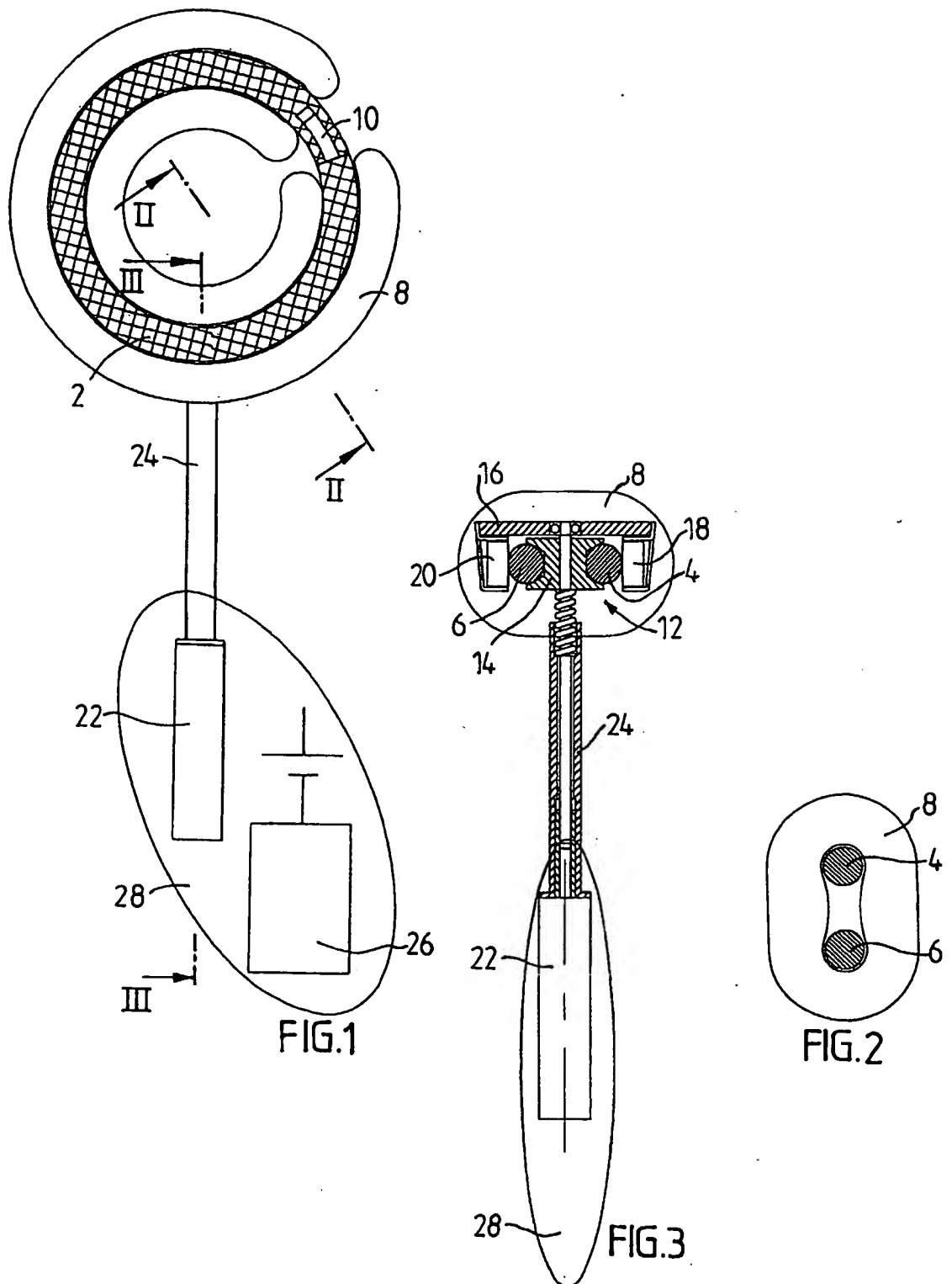
113. An apparatus according to claim 97, wherein the control signal comprises a wave signal comprising one of a sound wave signal including an ultrasound wave signal, an electromagnetic wave signal including an infrared light signal, a visible light signal, an ultra violet light signal and a laser light signal, a micro wave signal, a radio wave signal, an x-ray radiation signal, and a gamma radiation signal.

114. An apparatus according to claim 53, wherein the hydraulic means of the operation device comprises a fluid conduit, the reservoir forming part of the conduit.

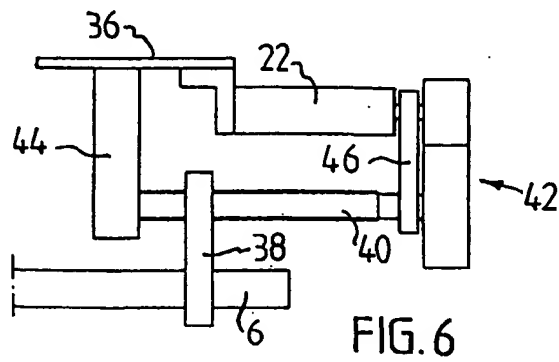
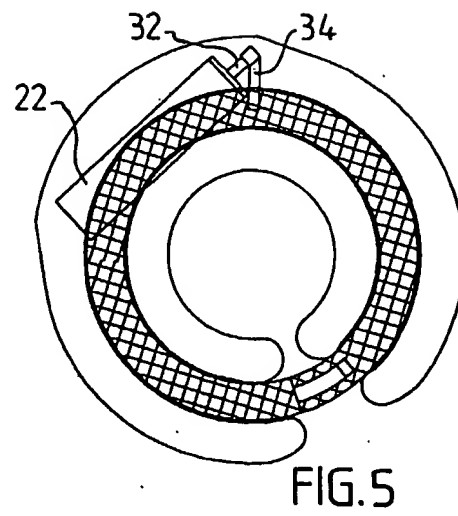
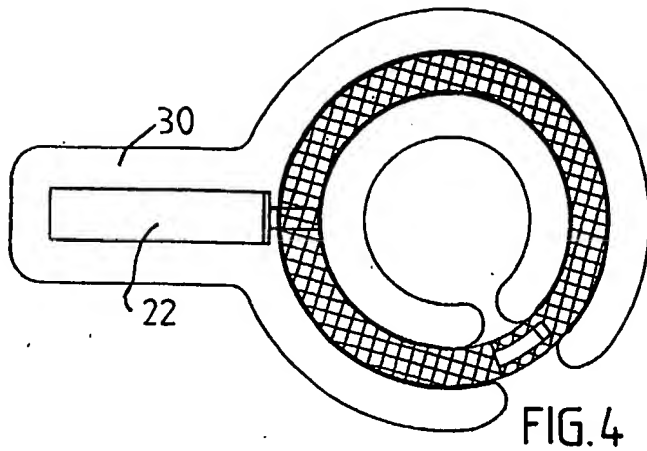
115. An apparatus according to claim 114, wherein the hydraulic means including the conduit are devoid of any non-return valve.

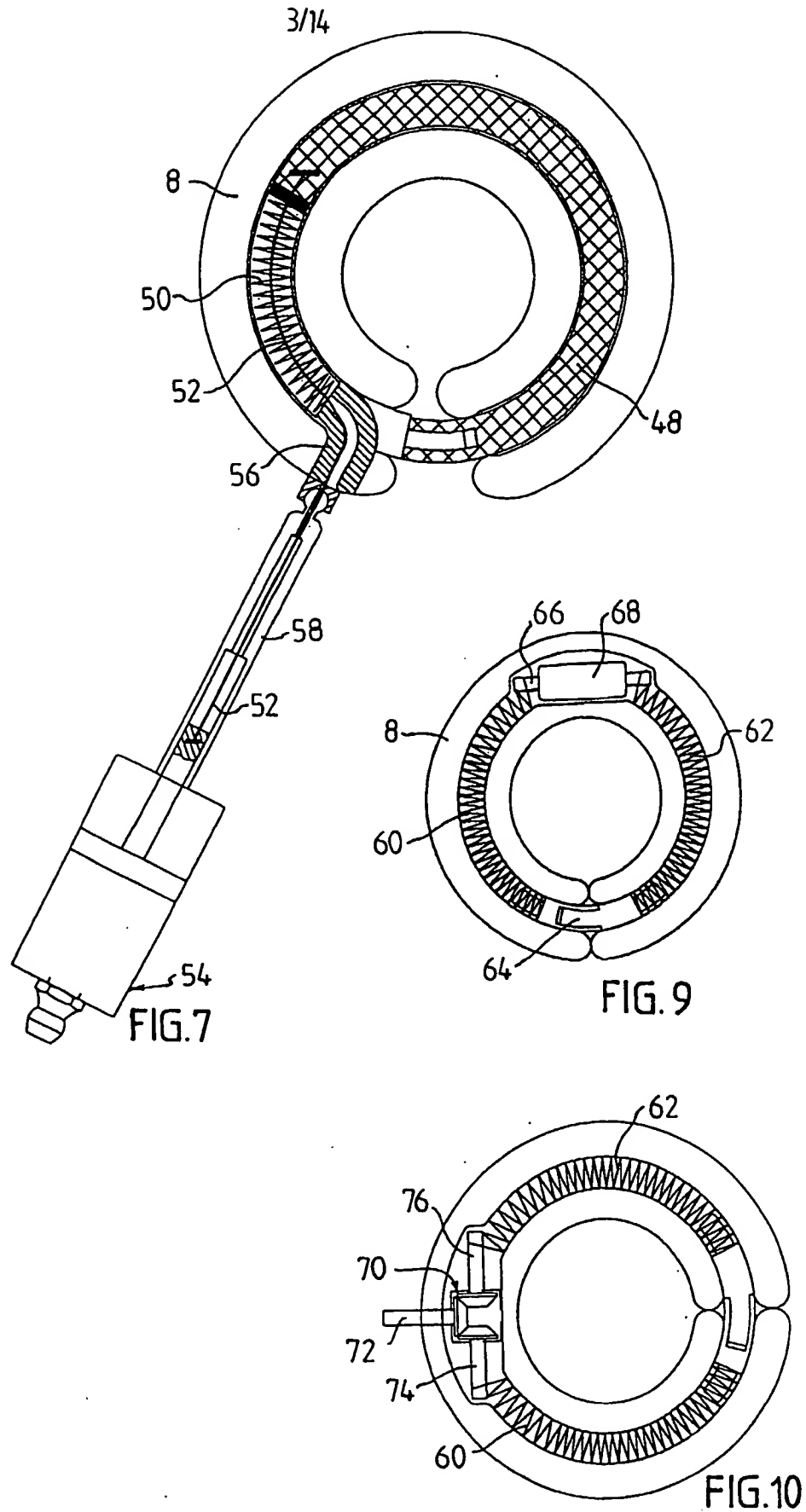
116. An apparatus according to claim 84, wherein the energy transfer means is adapted to transfer magnetic energy, non-magnetic energy, electromagnetic energy, non-electromagnetic energy, kinetic energy, non-kinetic energy, sonic energy, non-sonic energy, thermal energy or non-thermal energy.

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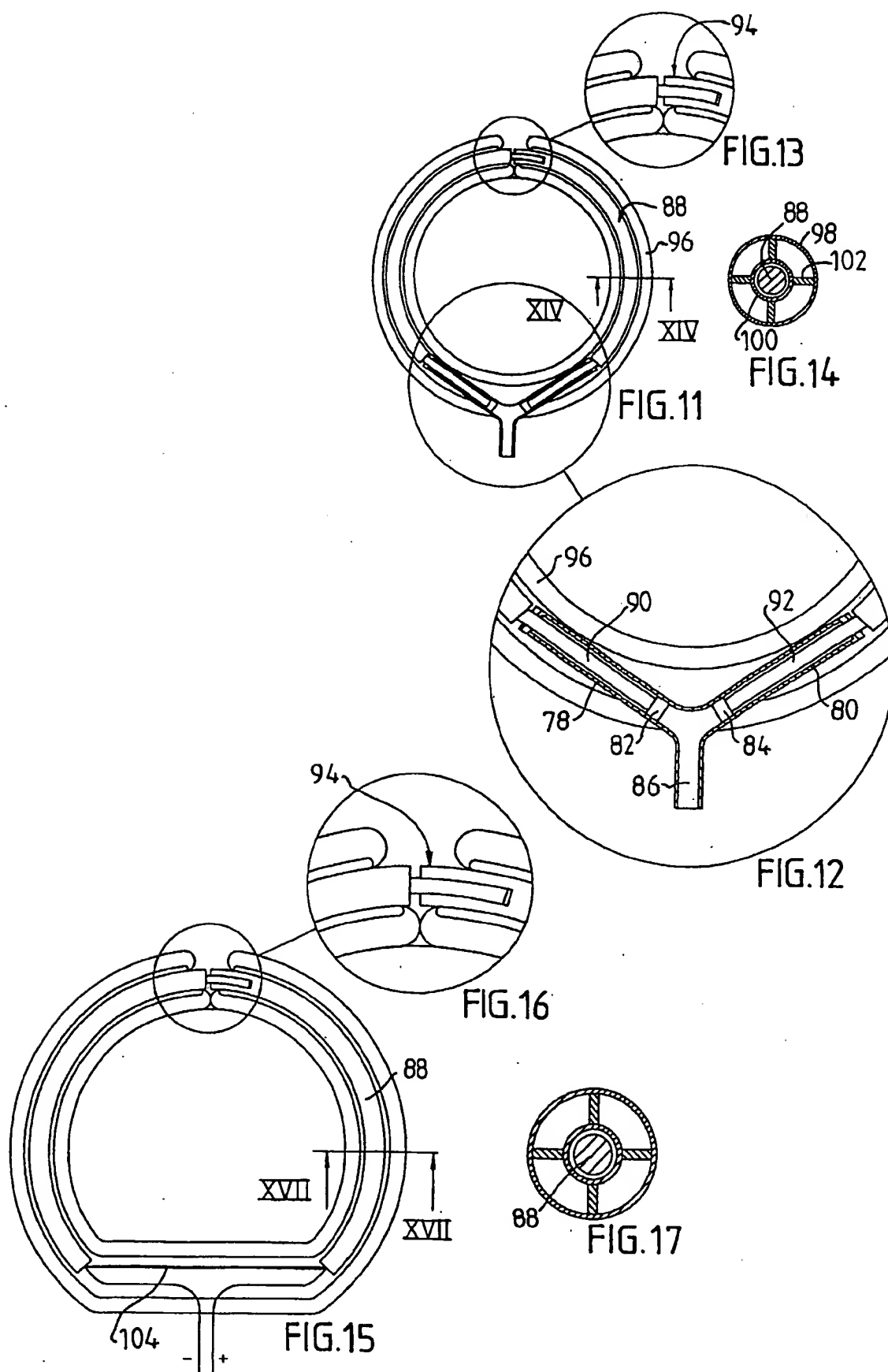


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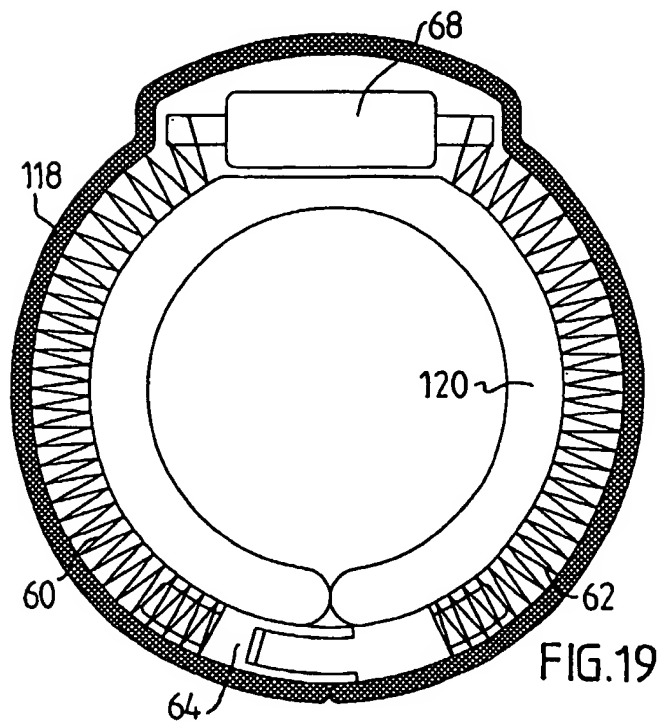
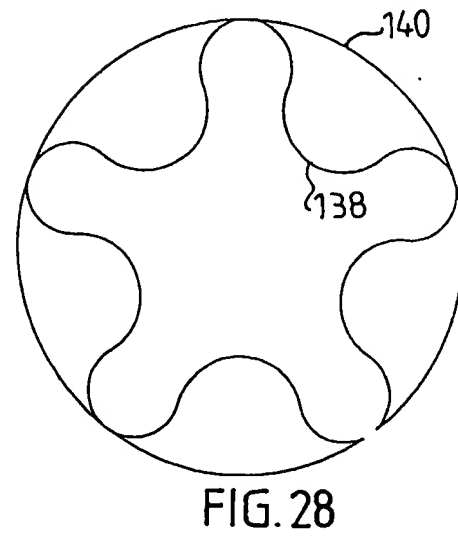
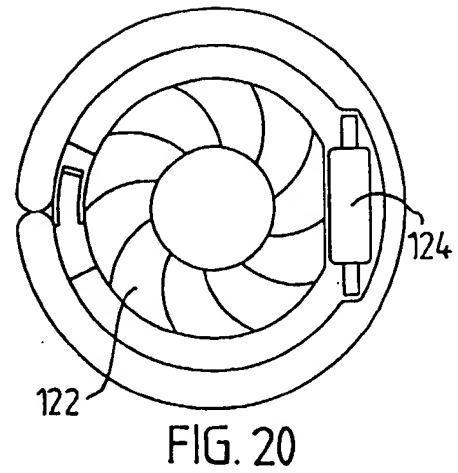
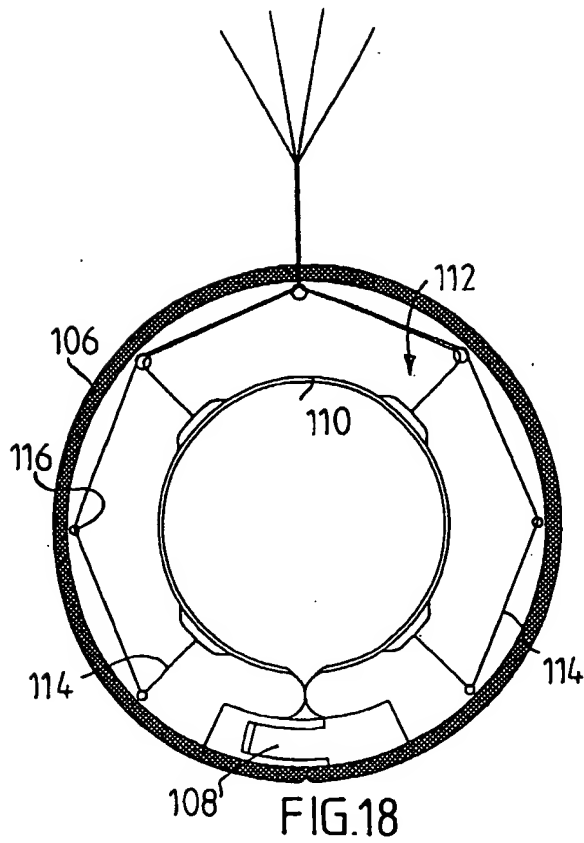




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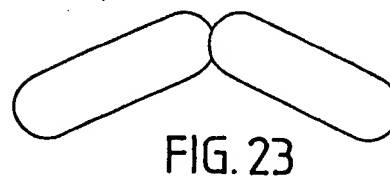
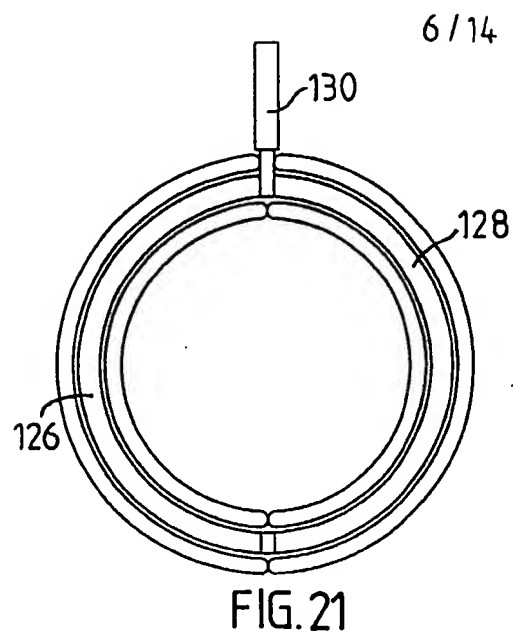
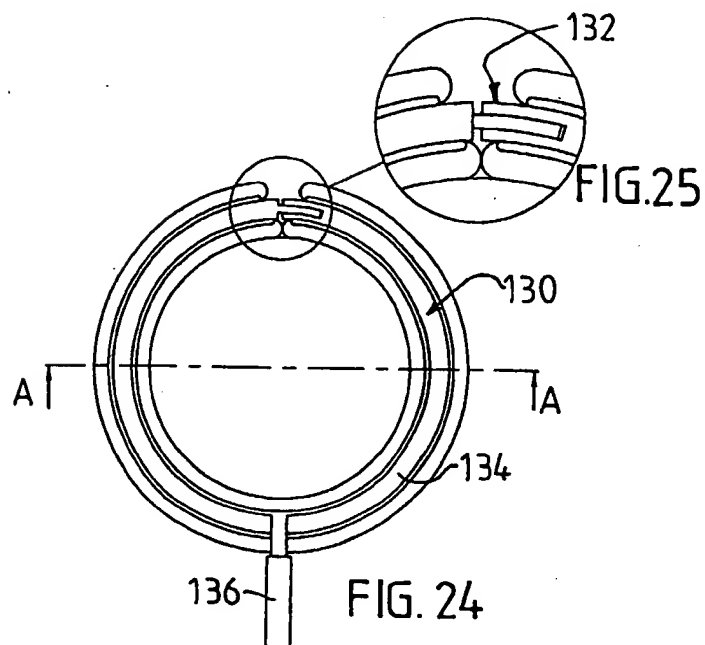
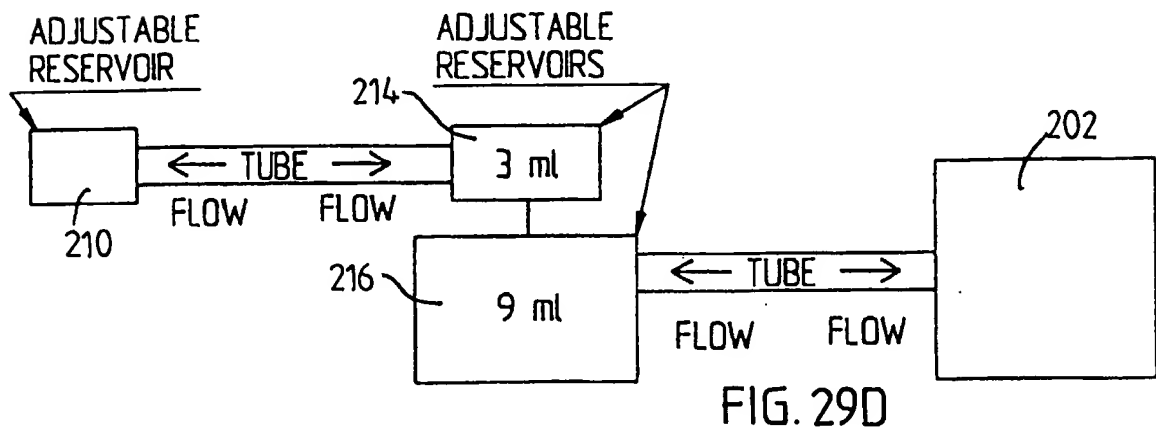
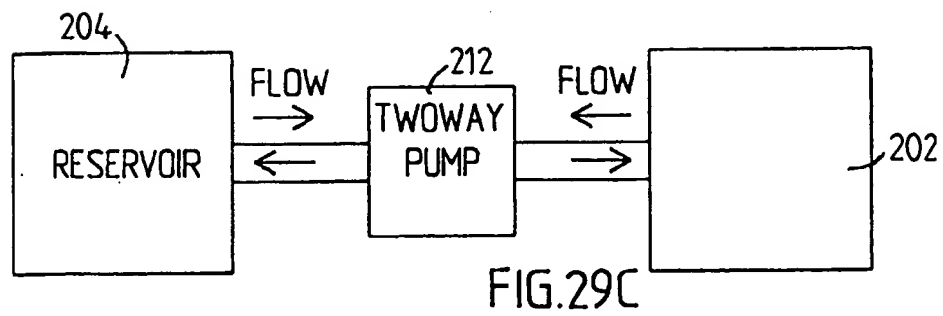
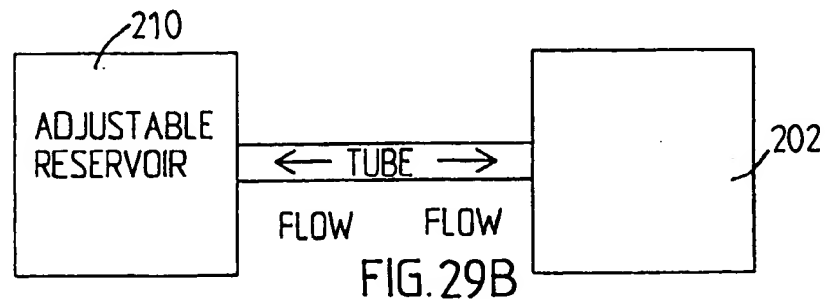
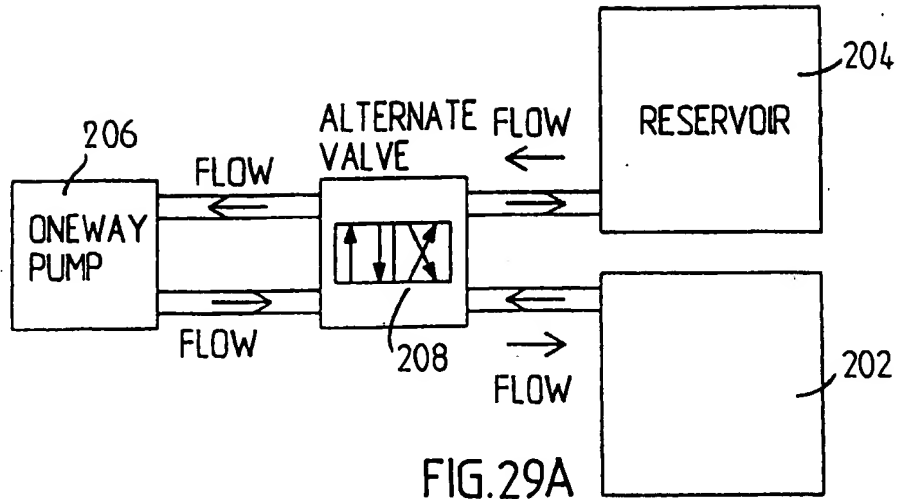


FIG. 26

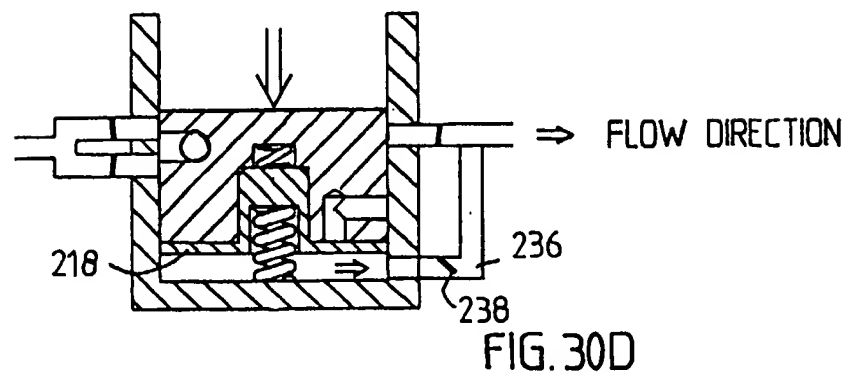
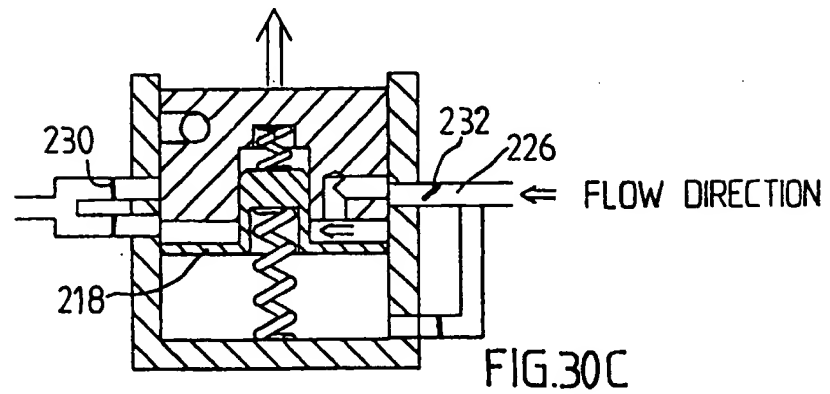
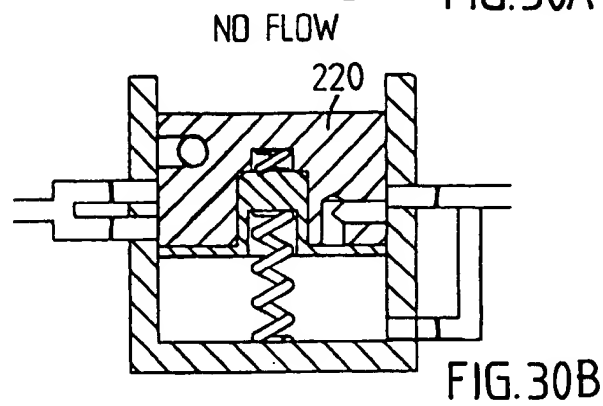
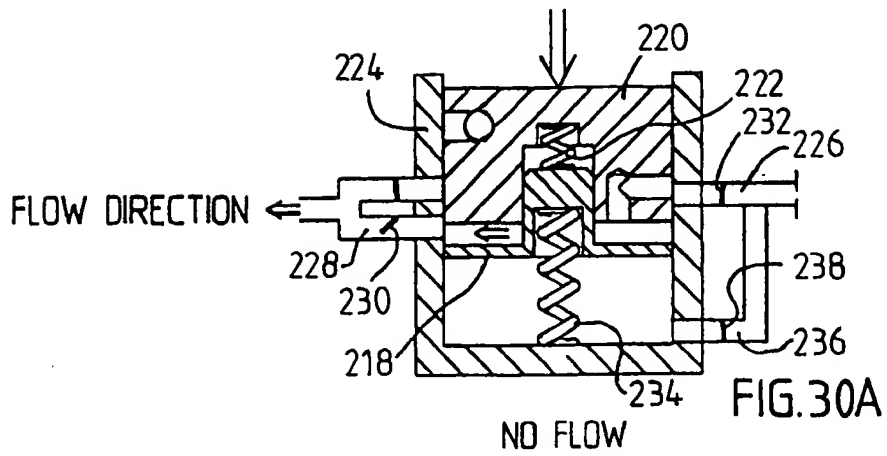
FIG. 27



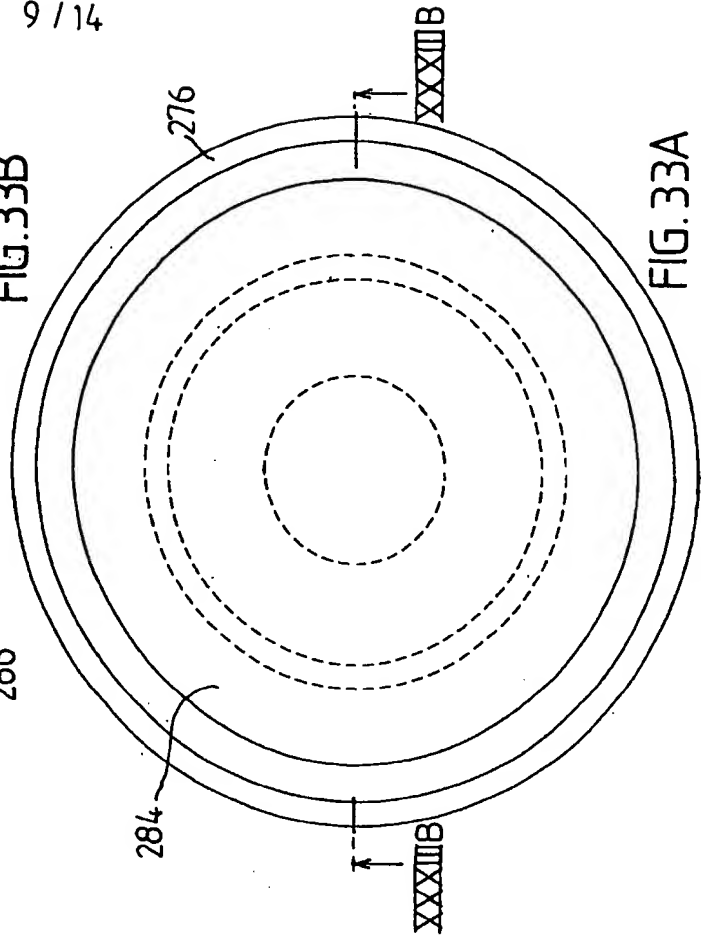
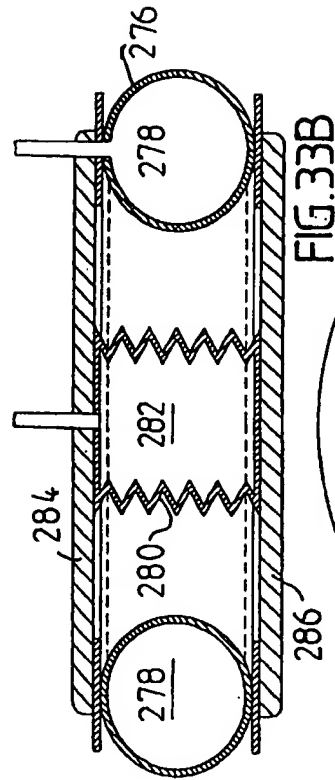
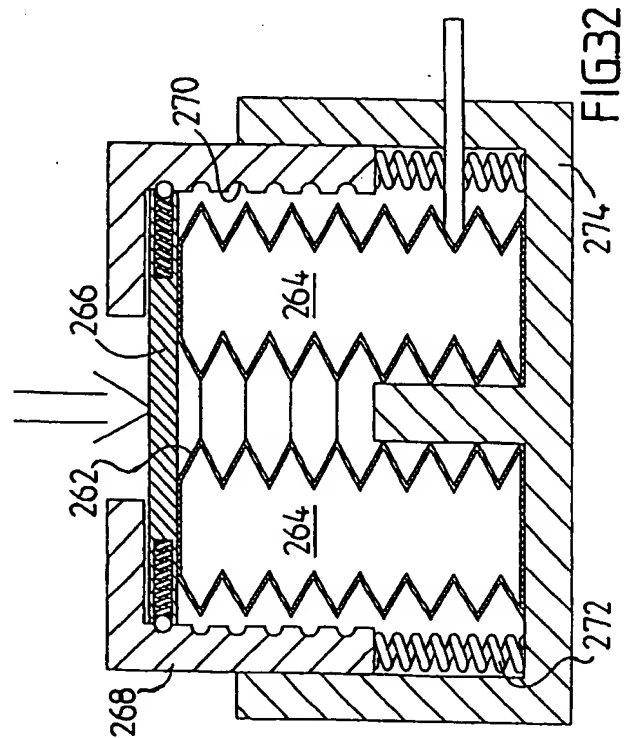
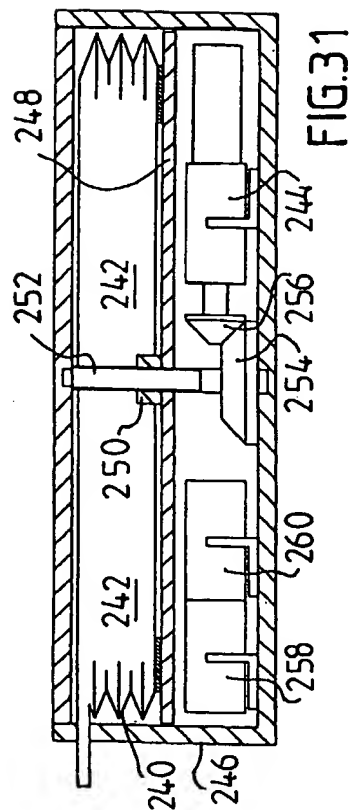
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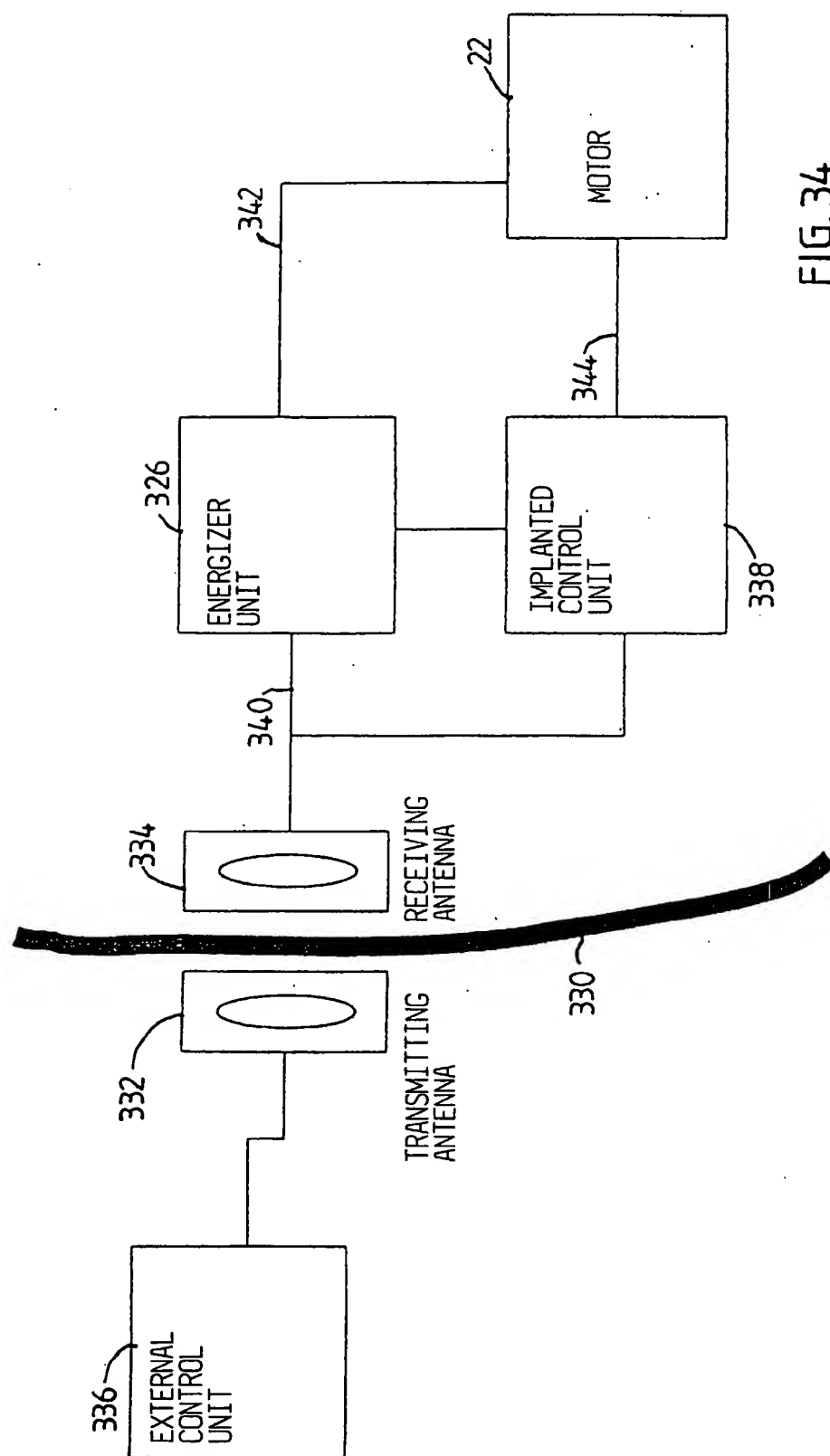


FIG. 34

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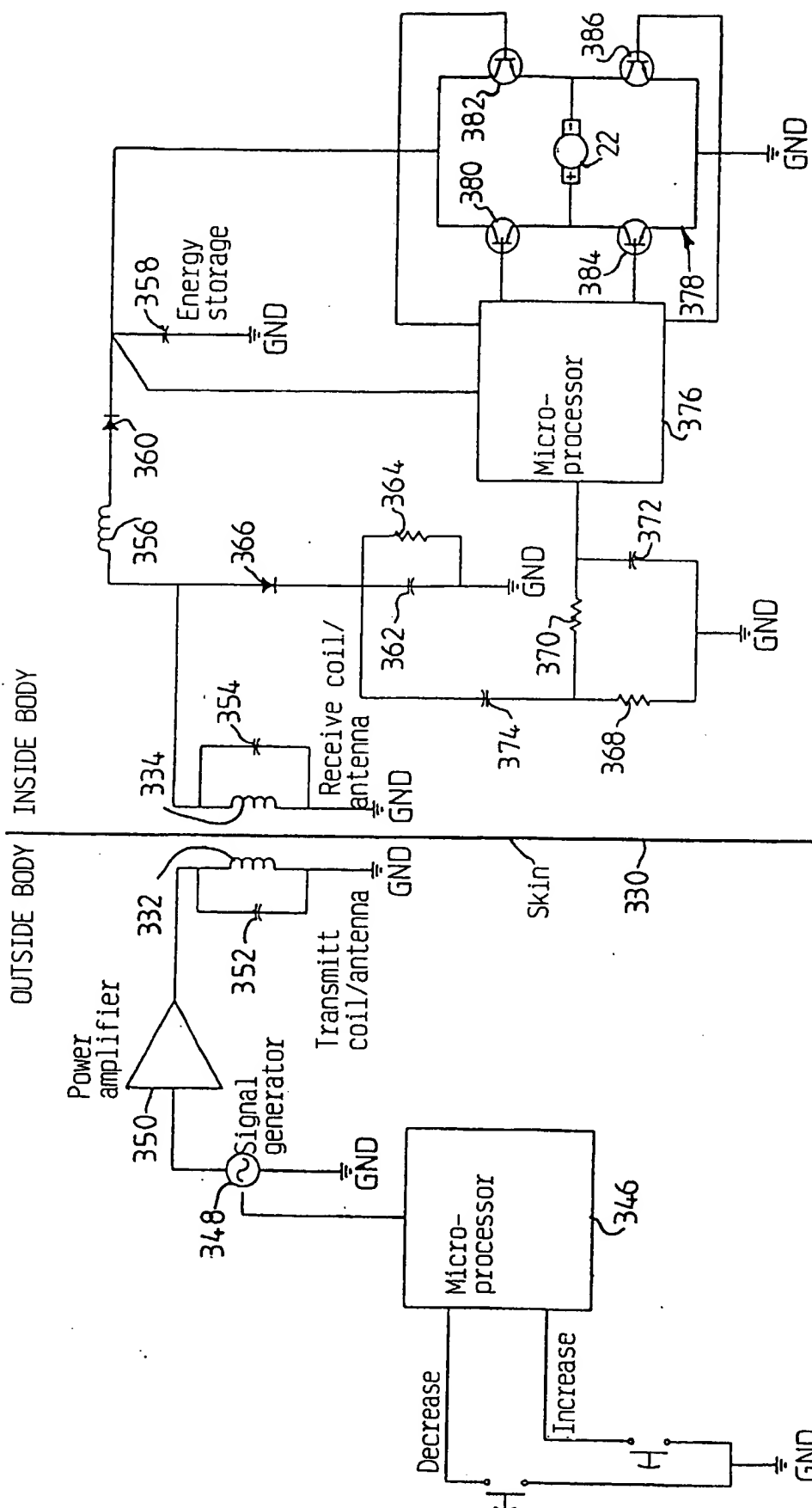


FIG. 35

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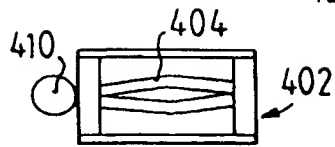


FIG. 36A

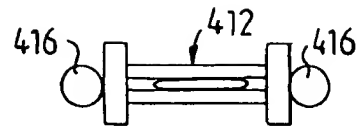


FIG. 37A

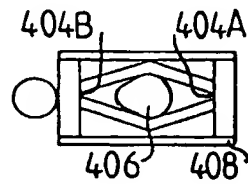


FIG. 36B

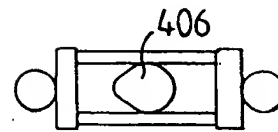


FIG. 37B

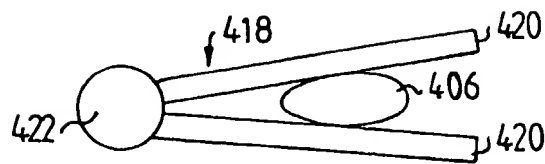


FIG. 38

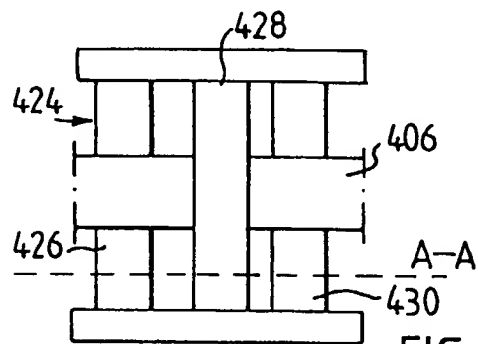


FIG. 39A

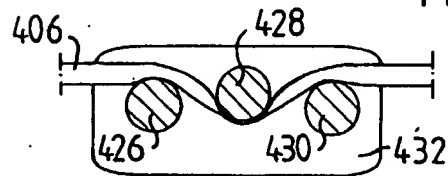


FIG. 39B

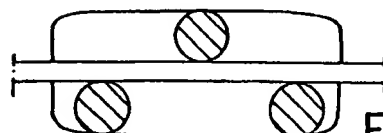
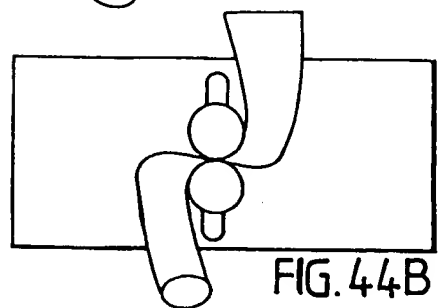
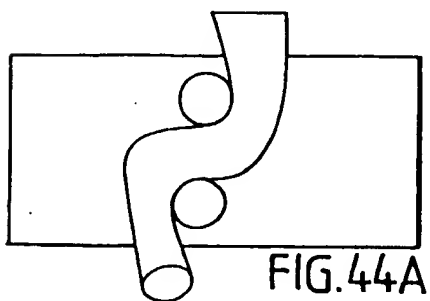
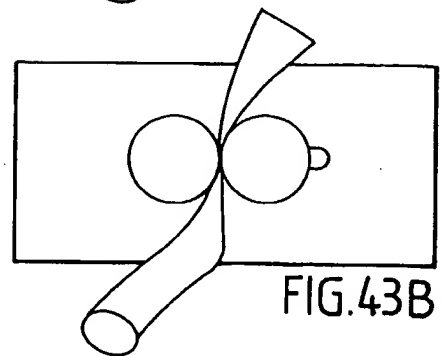
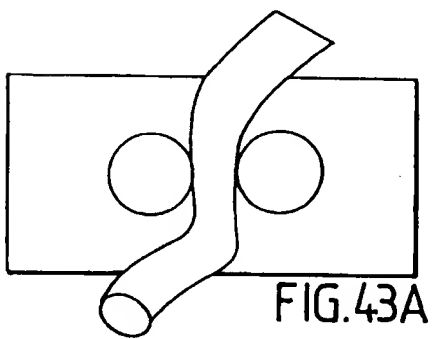
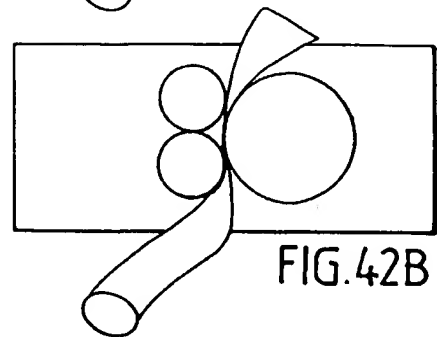
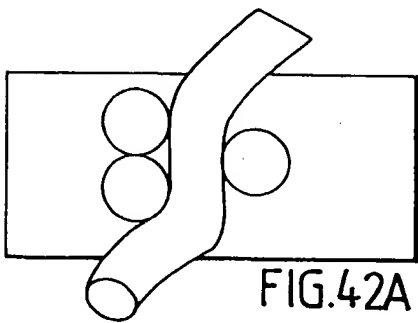
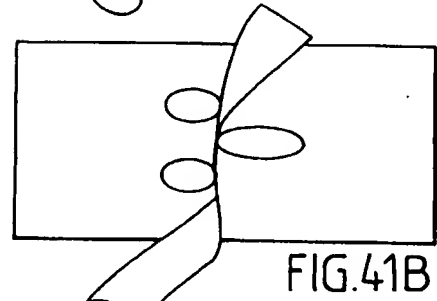
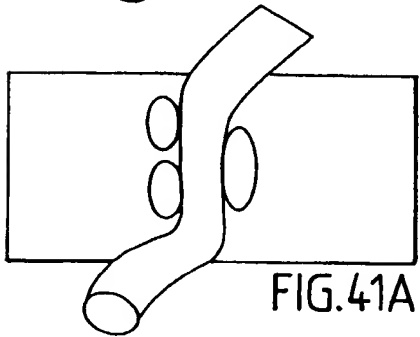
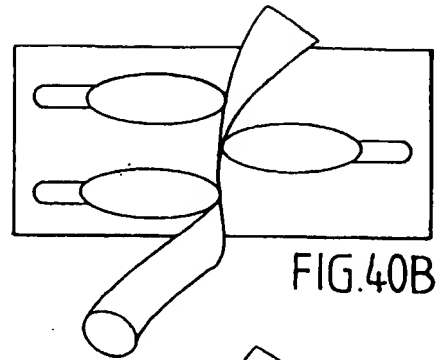
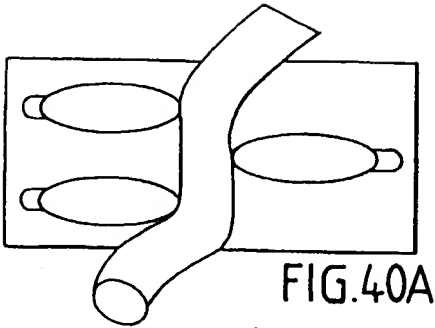


FIG. 39C

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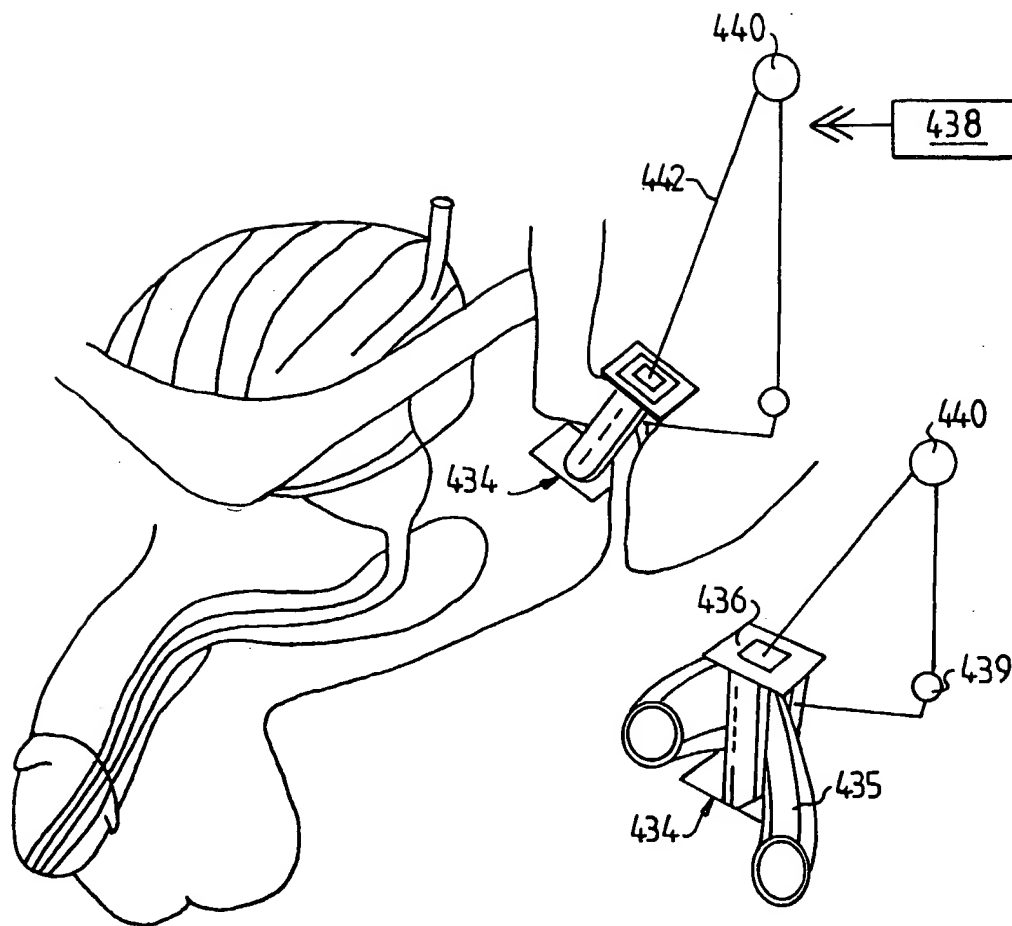


FIG. 45